### The CBM Triggerless Readout - Concepts and Prototyping



Workshop on Fast Realtime Systems Gießen, 8 April 2024

# **QCD Matter Physics: Theory and Experiment**



- Phase structure: 1st-order phase transition? Critical point? If yes, where?
- Equation of state?
- New QCD phases?

- Freeze-out points map the phase diagram
- Variation of collision energy allows to study different regions:
  - High energies (LHC, RHIC): vanishing density, high temperature
  - Lower energies (AGS, FAIR, GSI): high density, moderate temperature

## What's FAIR?



- Facility for Anti-proton and Ion Research
- A major new infrastructure for basic and applied research at GSI in Darmstadt, Germany
- 11 international partners
- Currently under construction start of operations 2028

### What's FAIR?



- Complex accelerator facility for a variety of physics
- Including slowly extracted nuclear beams for fixed-target experiments
- Full stripped heavy ions up to p = 12 GeV/c with intensities up to 10<sup>10</sup> ions / s.
- Symmetric nuclei up to 14 GeV/c; protons up to 30 GeV/c.



## A rich menu of observables





A. Andronic et al., PLB 697 (2011) 203



... some of which are really rare!

 $π^{-} \Lambda K^{+} K^{0}_{s} \eta \omega K^{-} \phi \Xi^{-} \Sigma^{+}$ 

0.5

### **CBM** in a Nutshell

- Measure charged pions, kaons, protons
- Measure electrons and muons
- Reconstruct weak decay topologies (hyperons, hypernuclei, charm)
- In fixed-target collisions in the FAIR-SIS100 energy range
- In a large acceptance
- With high precision
- With high statistics

Simulated Au+Au collision @ 12 AGeV (UrQMD)



Punchline: Moderate collision energy, very high rates

# CBM as it will be







### **Detector Systems**







**Ring-Imaging** Cherenkov detector for identification of electrons

**Transition-Radiation** Detector for identification of electrons and intermediate tracking

Muon System for

identification of

muons

Silicon Tracking System for tracking of charged particles

Micro-Vertex Detector for measurement of displaced vertices

detector for hadrons

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### The High-Rate Frontier





CBM design rate: up to 10 million collisions per second.

### Rate issues

- Radiation load on detectors and front-end electronics. Difficult, but not unsurmountable.
- Fast timing response of detectors and electronics
- HUGE data rate coming off the detectors

- Raw data size: ~100 kB / event (min. bias Au+Au @ 12 GeV/u).
- 10<sup>7</sup> events/s -> 1 TB/s raw data rate from the detector.
- Archival rate: 100 GB/s surely possible; 1 TB/s on the high side
- Data volume, assuming 2 months of operation per year (5 x 10<sup>6</sup> s): 5 EB / year!



Data selection in real-time (by about 3 OOM) is base of the CBM experimental concept.

### Trigger issues 1: Signatures are complicated





Complicated event topology!

Trigger decision requires track reconstruction and detection of the decay topology.

No chance to realize that in hardware logic. Has to be done in software.

# Trigger challenges 2: Event overlap (pile-up)



- Average time interval between events: 100 ns (Poisson process)
- Event duration: about 40 ns
- Close-by events will overlap in time
- Hard to detect by simple means; disentangling pile-up events requires close inspection (tracking)
- Not to be realized in a hardware trigger; to be done in software.



### Note bene: Fixed-target vs. collider experiments

### Collider

- Collisions at well-defined points in time (bunch crossing): external trigger from the machine clock.
- Macroscopic bunch crossing area: pileup events can be resolved in space.

### *Fixed-target*

- Continuous beam on target; continuous collisions.
- No beam trigger.
- All interactions take place in a thin target.
- Collision must be resolved in time.

## Meet the Challenges: Free-Streaming Readout



- No hardware trigger at all
- Continuous readout by autonomous FEE
- FEE sends data message on each signal above threshold ("self-triggered")
- Hit message come with a time stamp; readout system is synchronised by a central clock
- DAQ aggregates messages based on their time stamp into "time slices"
- Time slices are delivered to the online computing farm (FLES)
- "Event building" and storage decision on data selection is done in software in the FLES.

### **CBM Readout Architecture**



Self-triggered readout electronics Sends timestamped hit messages

#### Common Readout Interface (CRI)

FPGA-based PCIe board Interface to COTS nodes

#### FLES Interface Module (FLIM)

HDL module as subsystem interface Interface between detector specific and generic DAQ data path

#### First-level Event Selector (FLES)

Dual HPC cluster

Entry stage design data rate > 1 TB/s High-speed, RDMA-enabled network

# **Timeslice Building: Data Model**



- Partitioning of the data streams into short, context-free time intervals and encapsulating them into data transport containers called microslices
- Meta data provides all necessary information for data handling, e.g., start time
- Partitioning can be done locally by the subsystems
- Free choice of optimal detector data format for each subsystem

### **Online Data Selection**

- Time and charge calibration
- Cluster and hit reconstruction
- Track reconstruction
- Event construction
- Event analysis (w.r.t. trigger signature) and trigger decision
- Traditionally done offline
- To be done in real-time
- Needs very fast algorithms
- Massively parallel computing (multi-core, GPU) in the GSI Data Centre





### Issues of a Continuous Readout System

- The task of identifying events and inspecting them for signatures of interesting physics (rare observables) is shifted from electronic hardware to software.
- Precise understanding the timing behaviour of the detector and their readout electronics is mandatory!
- Detector noise and other backgrounds need to be understood and treated as well.



Simulated STS data (w/o thermal shielding), Au+Au @ 10A GeV, beam rate 10<sup>9</sup>/s, event rate 10<sup>7</sup>/s

### Data Inspection in Real-Time

- For a given event / data rate, the speed of the algorithms determines the required size of the online compute farm.
- For a given financial budget / size of the online farm, the speed of the algorithms determine the physics output of the experiment.
- High-performance online software is a pre-requisite for the successful operation of CBM.
  - Make optimal use of available parallel computer architectures: many-core, GPU, accelerators
  - Be flexible to upcoming new architectures
- Parallelism is the key word
  - Data-level parallelism: one timeslice per compute node (if GPUs are used: one timeslice per GPU)
  - Task-level and data-level parallelism within time slice
  - Simplest approach: one process per timeslice
  - Multi-threading on CPU within timeslice using OpenMP
  - Mult-threading on GPU using the XPU framework

# The Key: Finding Tracks Online

		100 AuAu minimum bias events at 10 AGeV			
Efficiency, %	3D	4D 0.1MHz	4D 1MHz	4D 10MHz	
All tracks	92.5 %	93.8 %	93.5 %	91.7 %	
Primary high-p	98.3 %	98.1 %	97.9 %	96.2 %	
Primary low-p	93.9 %	95.4 %	95.5 %	94.3 %	
Secondary high-p	90.8 %	94.6 %	93.5 %	90.2 %	
Secondary low-p	62.2 %	68.5 %	67.6 %	64.3 %	
Clone level	0.6 %	0.6 %	0.6 %	0.6 %	
Ghost level	1.8 %	0.6 %	0.6 %	0.6 %	
True hits per track	92%	93 %	93 %	93%	
Hits per MC track	7.0	7.0	6.97	6.70	

High efficiency for primary tracks Rate effects become visible above 1 MHz interaction rate



Good scaling behaviour: well suited for many-core systems

## Resolving event pile-up



- Reliable event resolution requires track reconstruction.
- Tracking operates on stream of detector hits, without event association.
- Needs a 4d track model (x, y, z, t, q/p); sophisticated algorithm.
- Reduces the temporal event extension from ~40 ns to ~3 ns.
- Runs in software no way to have it in hardware.

### Not all triggers are complicated...







- The muon system has a very simple measurement principle.
- Trigger requires two tracks to pass the absorbers at the same time.
- Simple algorithm; implementation on various platforms (CPU / GPU) investigated at VECC.

Table 1: Results for the event selection algorithm on the Tesla GPU								
#	#	#	GPU	CPU-	CPU	Speed-		
Events	blocks	threads	Time	GPU	Time	Up (CPU		
			(ms)	Transfer	(ms)	$\operatorname{time}/\operatorname{GPU}$		
				$\operatorname{Time}(\mathrm{ms})$		time)		
1000	32	32	23.9	1.2	16.38	0.69		
2000	64	32	27	2.9	32.40	1.20		
3000	64	64	29	6.7	48.60	1.68		
4000	64	64	32	9.4	64.83	2.03		
5000	128	64	33.9	10.1	81.16	2.39		
10000	128	128	48.9	12	161.67	3.31		
20000	256	128	89.7	14.5	320.24	3.57		
40000	512	128	140.7	19.7	640.25	4.55		
80000	1024	128	289.8	28.3	1280.39	4.42		

V. Singhal et al., Comp. Phys. Comm. 252 (2020) 107190

## Selectivity and operation modes

Not all observables require or allow a highly selective trigger:

- Some have no trigger signature: fluctuations, low-mass electron pairs
- Some are not rare: all bulk observables
- Some allow lesser selectivity: high-mass electron pairs

Of course, CBM can also be operated at lower rates!

Recordable min. bias rate (w/o online selection): 10<sup>5</sup> events/s

N.b.: High-rate operation allows to take selective (triggered) data together with min. bias (downscaled to saturate the bandwidth).

### Our testbed: mCBM



- First runs 2021, 2022 (w/o online processing, all data to disk)
- Next benchmark run: 2024, applying online data selection

- A full-system sandbox with detector prototypes / pre-series components
- Study detectors after integration
- Verify free-streaming read-out and data transport and online data processing
- Benchmark online data processing
- Gain operational experience

### mCBM Data Transport System



### mCBM: Data Path Performance



### mCBM: Data Challenges

- Until 2022: No online data processing; dumping raw data (full timeslices) to disk
- Development of online processing chain with re-play of archived raw data (emulates DAQ)
- Allows to study and benchmark timeslice building and online data processing prototypes
- Gain operational experience interplay of owned resources (entry nodes) with shared resources (compute nodes).



DC 3 (December 2023) Unpacking + event building + local reconstruction

### mCBM: Inclusion of Track Reconstruction





DC 4 (February 2024) Unpacking + event building + local reconstruction + track reconstruction (not yet multi-threaded)

### The state of our art...

- Complete event reconstruction developed for offline purposes.
- Ongoing: adapting / porting / optimising for online usage.
- Development and testing on real data (mCBM) and simulated data (full CBM)



### mCBM: Achievements and Next Steps

- Multi-core parallelization (OpenMP) of all reconstruction steps (STS, TOF, tracking).  $\checkmark$
- STS unpacking and reconstruction ported to GPU and tested on VIRGO nodes.  $\checkmark$
- Commissioning beam time March 2024: applied online processing during data taking; minimum-bias trigger  $\checkmark$ based on digi multiplicity; data reduction by a factor of four.
- Benchmark beam time May 2024 (Ni+Ni): Application of full online reconstruction and trigger on displaced • vertices (Lambda).

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### Summary: From mCBM to CBM

















A long and winding road - but we are some way up already.