



MAX-PLANCK-INSTITUT
FÜR PHYSIK



Upgrade of the Neural Network Track Trigger for Belle II

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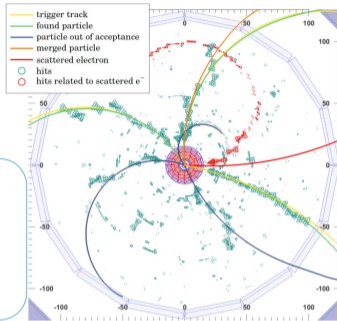
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MPI & LMU & TUM

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- Felix Meggendorfer
- Simon Hiesl
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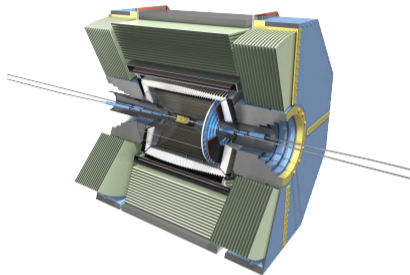
Focus of the
MPI/LMU/TUM
group:

Track Triggers

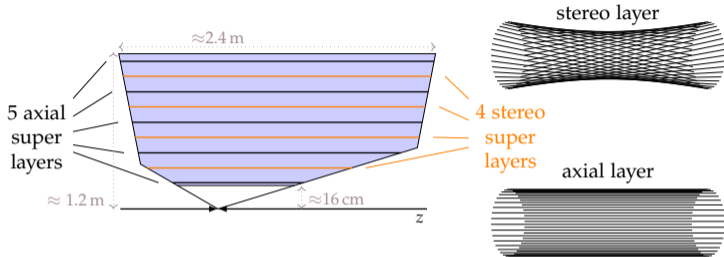
The Central Drift Chamber (CDC) of Belle II



The Belle II Detector



The CDC



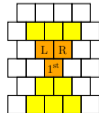
- TS = Wire pattern compatible with a crossing track \rightarrow 2336 TS in 9 Super Layer (SL)

Track Segment (TS)

(a) Super Layer 0



(b) Super Layer 1-8

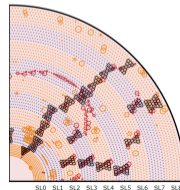
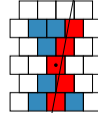


Track Segment Hit

(a) Super Layer 0



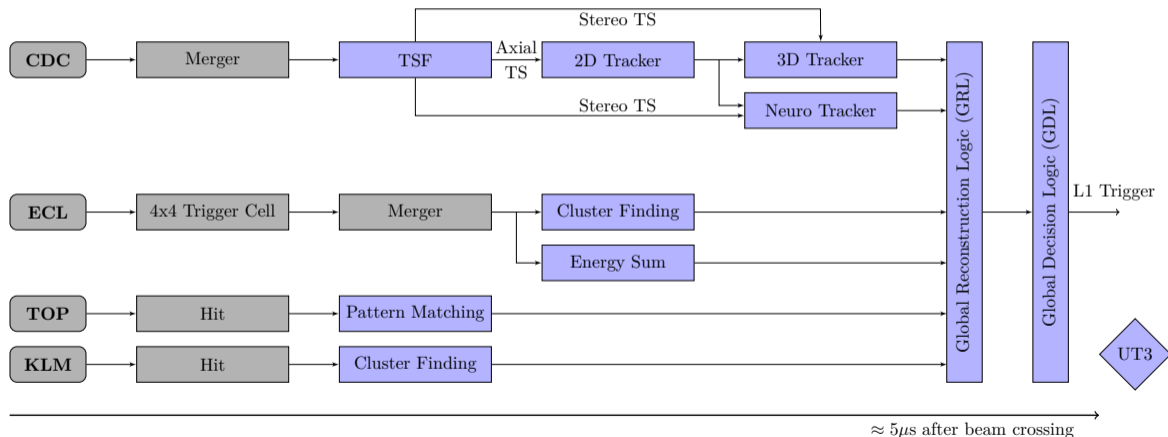
(b) Super Layer 1-8



The Old L1 Trigger Pipeline

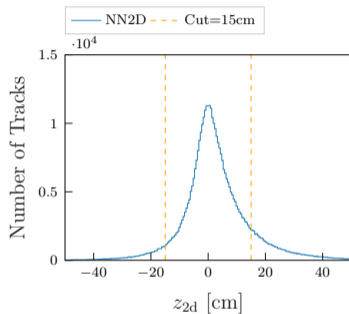
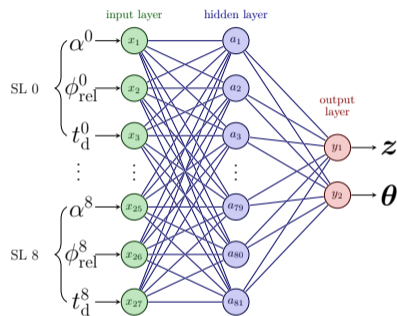


- Present implementation → 2DFinder and Neuro Tracker on separate FPGA boards
- The available latency for the Neuro Tracker is just **300ns**

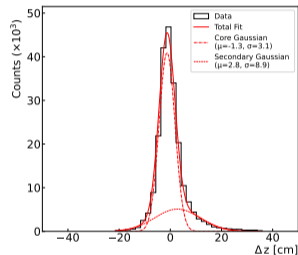


z-Vertex and polar emission angle prediction with a neural network:

2D track + Stereo TS $\implies z + \theta$ prediction (Current Network: One hidden layer with 81 nodes)



z-Resolution

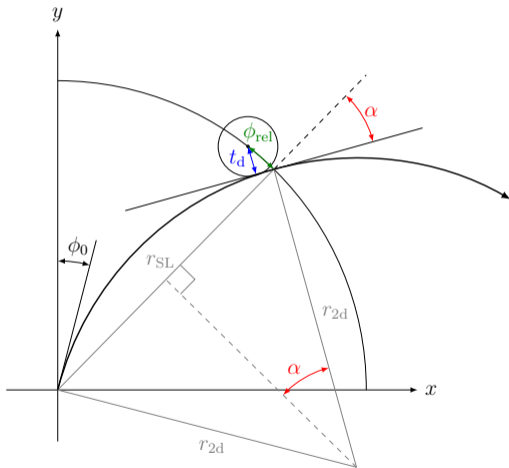


$\implies z$ -cut of ± 15 cm used

Single-Track-Trigger: Low multiplicity trigger activated if the momentum is above 0.7 GeV
(S. Bähr et al., arXiv:2402.14962)

$$p[\text{GeV}] = \frac{1}{\omega[1/\text{m}] \sin(\theta) 0.3 B[\text{T}]} \geq 0.7 \text{ GeV}$$

From the track finding (Hough transformation) we get: $\omega = \pm 1/r_{2d}$ and ϕ_0



With the TS information

$$\phi_{\text{wire}}, n_{\text{wire}}, r_{\text{SL}}, \sigma_{\text{LR}}, t_{\text{d,wire}}$$

we can calculate:

$$\alpha = \arcsin\left(\frac{1}{2} \frac{r_{\text{SL}}}{r_{2d}}\right)$$

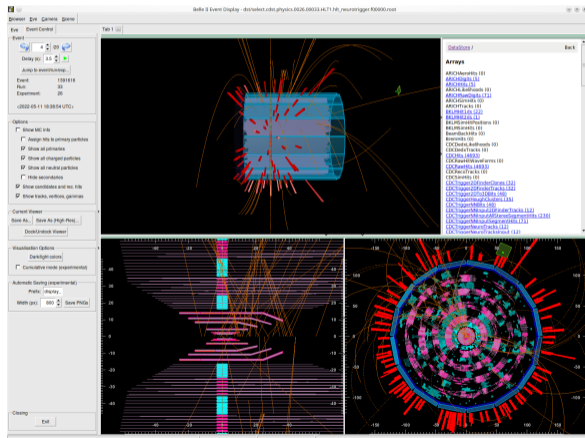
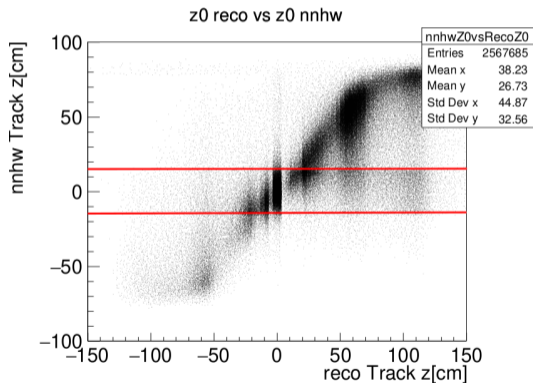
$$\phi_{\text{rel}} = \phi_{\text{wire}} - n_{\text{wire}} \cdot \left(\frac{\phi_0 - \alpha}{2\pi}\right)$$

$$t_{\text{d}} = \sigma_{\text{LR}} \cdot (t_{\text{d,wire}} - t_{\text{d,min}})$$

Problems with the L1 Neural Network Trigger



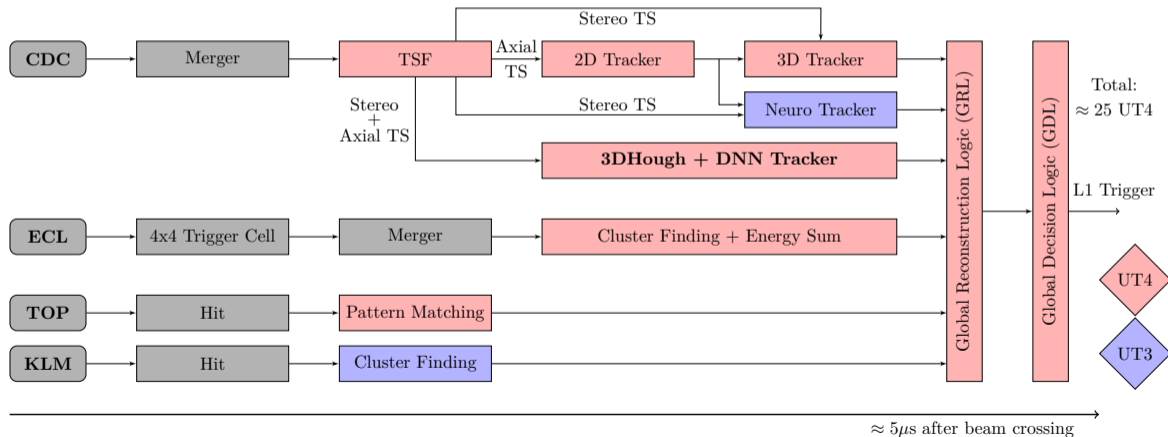
- "Feed-Down" effect: Background tracks \rightarrow Vertex tracks
- High number of 2D track candidates from the 2DTracker when the background is high \Rightarrow Many Fake-Tracks using stereo background hits



The New L1 Trigger Pipeline



- New implementation → 3DFinder and Neuro Trigger on the same (new) FPGA board (UT4)
- The available latency for the Neuro Tracker is increased to **700ns**
- Neural networks with three or four hidden layers are possible



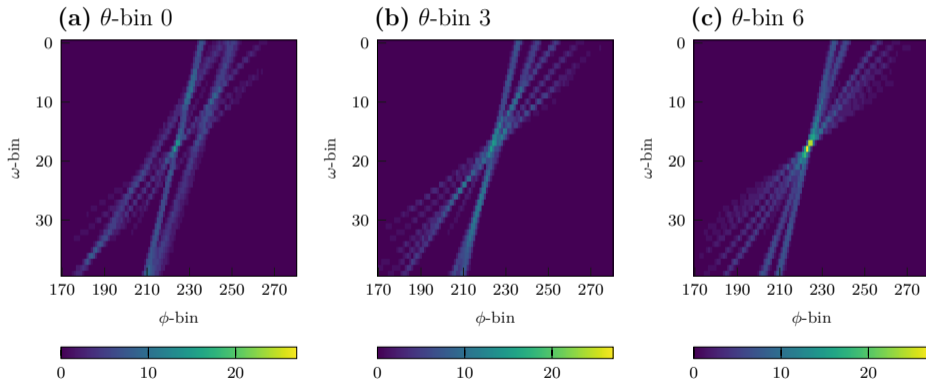
Extension to 3D: The 3DFinder



New curve parameter: Polar angle $\theta \implies$ 3D-Hough space

- 9 bins in $\theta \in [19, 140]^\circ$, 384 bins in $\phi \in [0, 360]^\circ$, 40 bins in $\omega \propto q \cdot p_T^{-1}$, $p_T \in [0.25, 10]$ GeV/ c

Vertex assumption: The track originates from $(x, y, z) = (0, 0, 0)$ (IP)



\implies Intersection point yields ω , ϕ and θ

Clustering Algorithm in 3 Dimensions

Original algorithm (Sebastian Skambraks): DBSCAN

Impossible to implement on an FPGA

(non-deterministic length \implies latency not fixed)

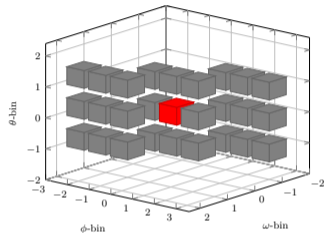
Update: A new clustering option implemented in basf2:

Fixed Volume Clustering

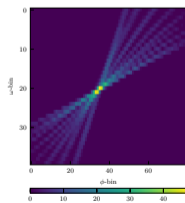
Three steps, repeated **iterations** times:

- Step 1: Global maximum search on Hough space
- Step 2: A fixed shape is put around the maximum
 - ▶ The weights in this shape are added up (total weight)
 - ▶ If total weight \geq `mintotalweight` and peak weight \geq `minpeakweight` the cluster is saved
 - ▶ All hits (TS) are extracted and have to pass two TS cuts
- Step 3: Cells around the global maximum are set to zero (“Butterfly-Shape” cutout)

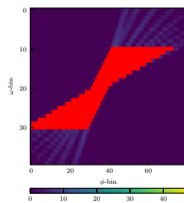
Fixed shape:



(a) Complete Cluster



(c) Cutout

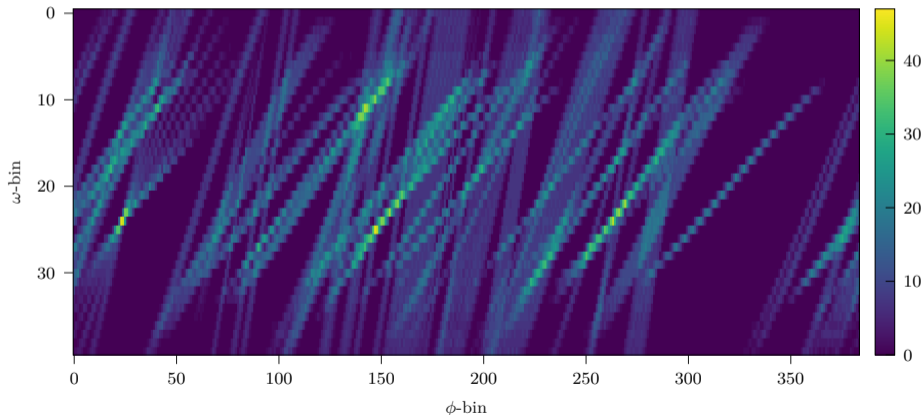


Real Data Analysis: Experiment 26 Single Track Events



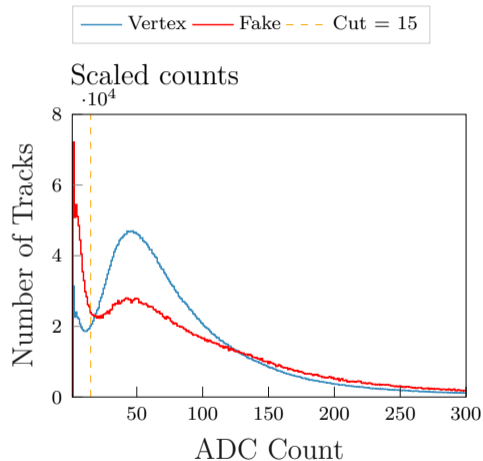
- Very high backgrounds were observed shortly before the long shutdown
- The Hough spaces contain a lot of fake track segments

θ -bin 3: Exp. 26, run 1832, HLT1, f00005, event 79 (comp)

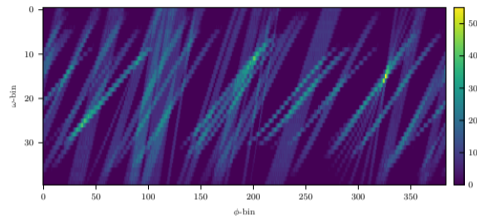


Introducing a Cut on the ADC Count

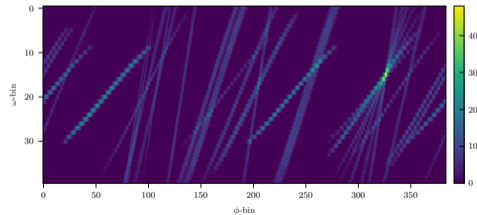
- A cut on the ADC count of the wires has been made possible by the new UT4 boards



(a) θ -bin 2: No adccut

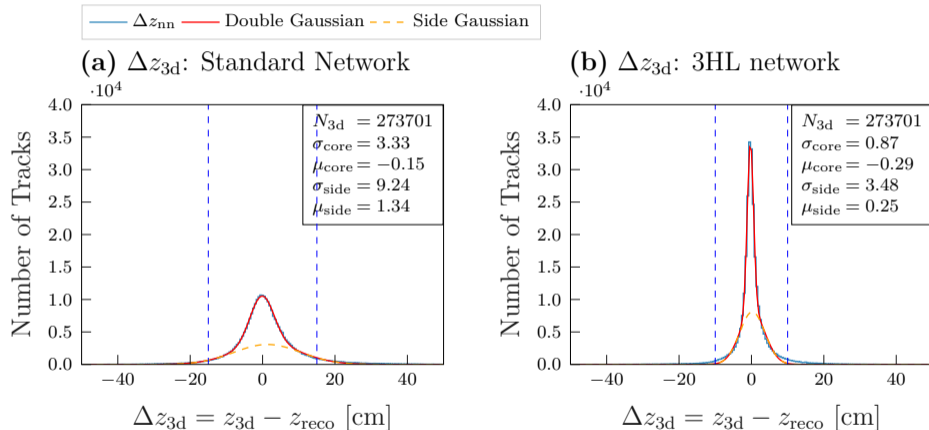


(b) θ -bin 2: adccut=10



⇒ Reduction of noise using a cut on the ADC count

Timo Forsthofer (master's thesis, next presentation):

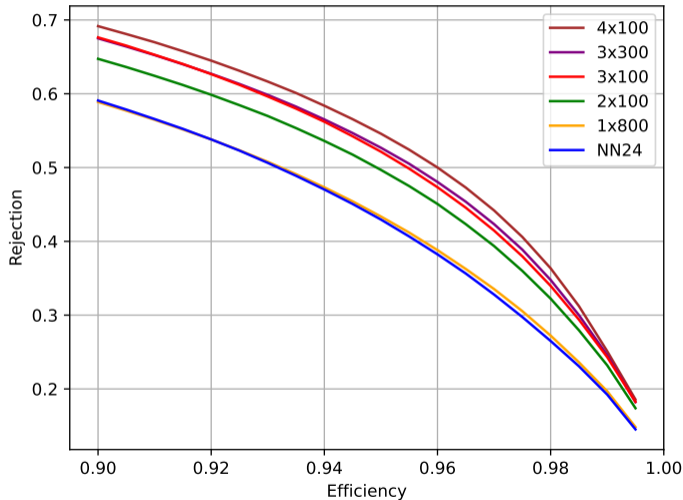


\Rightarrow Cut reduction from ± 15 cm to less than ± 10 cm possible due to better resolution

Rejection vs. Efficiency of Different Network Architectures



Timo Forsthofer (master's thesis, next presentation):



- Deeper neural networks are considerably better than wide neural networks
- The performance is restricted by the limited input (Only 9 TS at the most)

Efficiency for single track events: Cut at ± 10 cm

adccut	Efficiency 3D	Efficiency 2D
No Count	94.1%	94.0%
10 Counts	96.3%	95.3%

Fake-Rate for all found tracks:

adccut	Fake-Rate 3D	Fake-Rate 2D
No Count	13.1%	31.6%
10 Counts	5.8%	13.5%

But: Neural network not trained for 3D candidates at the moment (see presentation by Timo Forsthofer)

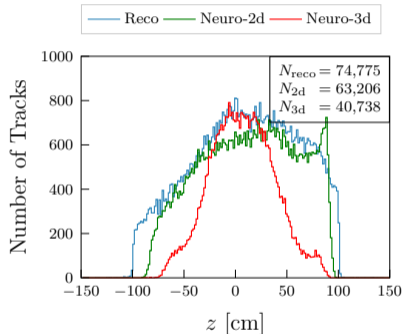
Conclusions and Next Steps

Using the 3DFinder has multiple advantages over the present 2D model with additional stereo TS selection:

- Automatic suppression of tracks outside the interaction region (candidates implicitly originate from the IP)
- Better track segment selection \implies Better resolution
- Implementation of track finding and network computation on the same FPGA board \implies Deep neural networks
- Smaller Fake-Rate
- Higher efficiency

Currently:

- Implementation of the 3D Hough method on UT4 FPGA boards (Kai Unger)
- Improved neural network architecture (Timo Forsthofer)
- Retraining with unbiased data from the new data taking



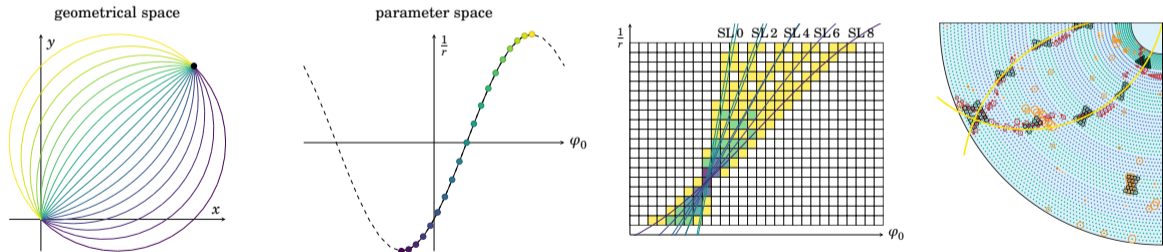


Backup

Which TS belong to a real track?

TS selection using a two-dimensional Hough transformation:

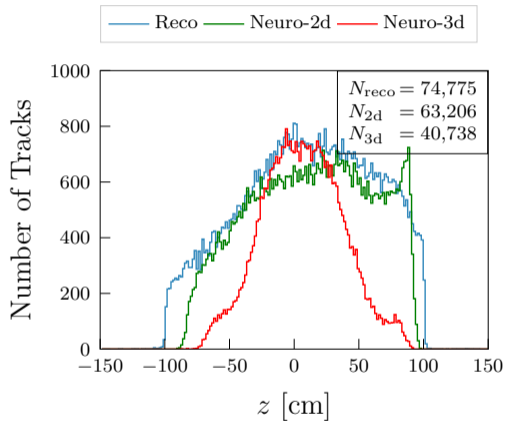
- Axial hit in CDC (TS) gets transformed to a curve in parameter (Hough) space
- Intersection point yields the track parameters ϕ and $r_{2d} \propto p_T$



⇒ 2D track candidate

The Neuro Trigger has been running since January 2021 years with remarkable success.

- Promising results from **Particle Gun** single tracks ($z_{\text{reco}} \in [-100, 100]$ cm)
- The number of found tracks falls quickly with large $|z|$



Parameter optimization did not sufficiently solve the following problems:

- Resource heavy on the hardware, non-deterministic length, difficult to implement
- Clusters can get very large \implies Very bad resolutions for some tracks
- Very high fake rates when using nominal phase-3 background (3 fakes for 1 signal)

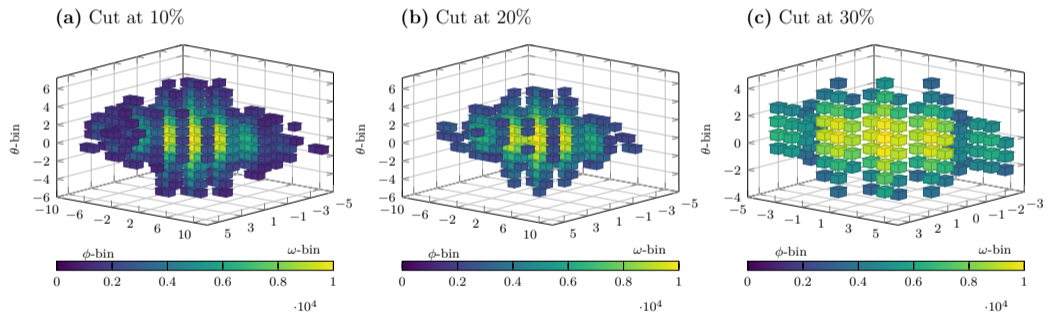


Figure: The cut percentage defines how often (on average) a cell was present in the clusters.

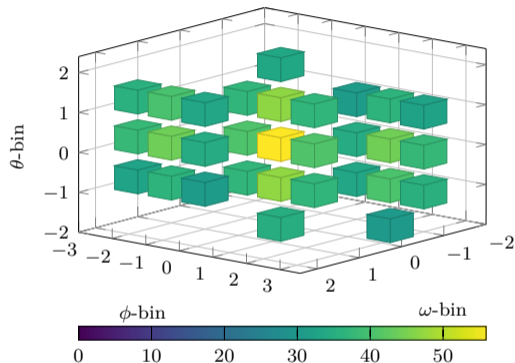
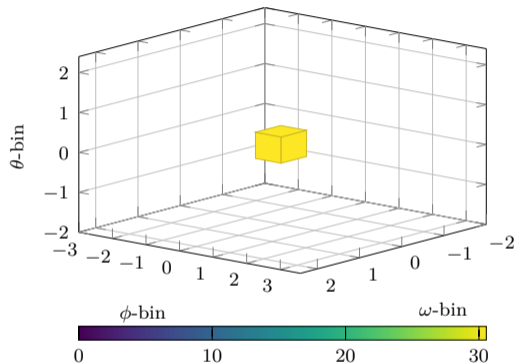
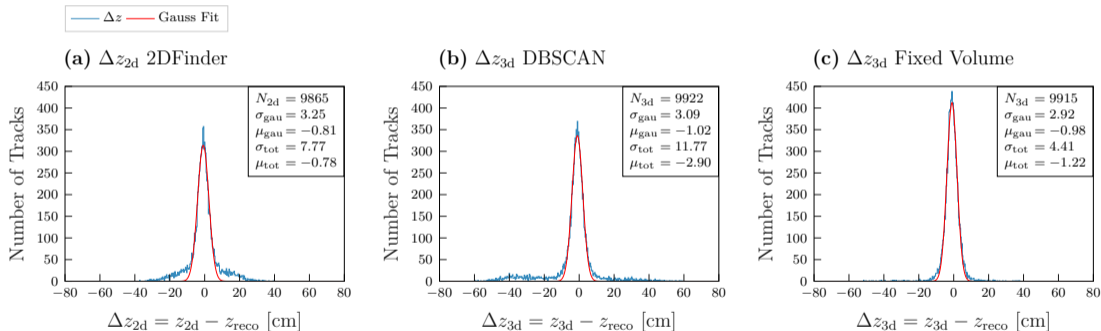
(a) $\text{weight} \geq 30$ (b) $\text{weight} \geq 30$ 

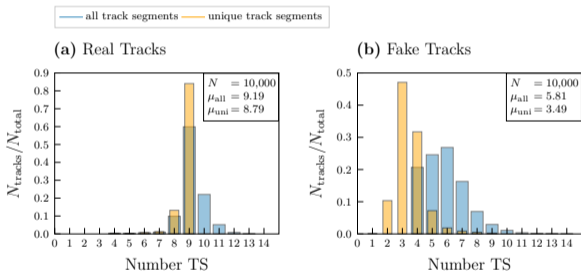
Figure: The average cluster weights (10000 clusters) above a weight of 30: (a) Real tracks with nominal phase-3 background, (b) Fake tracks from only nominal phase-3 background.

New idea: Fixed cluster shape clustering

- 10 000 single IP tracks
- The efficiency and resolution are high with the fixed volume clustering (plot (c)):



- Very high fake rates are observed \implies Solution: Cut on the number of hit super layers



Background rate per event (10 000 neutrinos):

Clustering	minhits	minsuper	N_{3d}^{all}
DBSCAN	4	0	29 424
DBSCAN	6	0	11 350
Fixed Volume	5	5	783

- Default DBSCAN: **290%**
- Fixed Volume with minsuper = 5 cut: **6%**