

# Reinterpretation of the Belle II $B^+ \rightarrow K^+ \nu \bar{\nu}$ result

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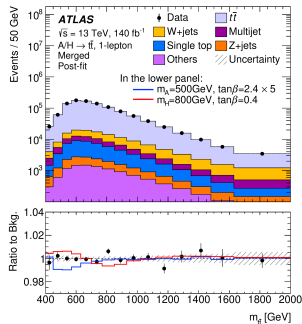
September 9, 2025

# New measurement, new analysis?



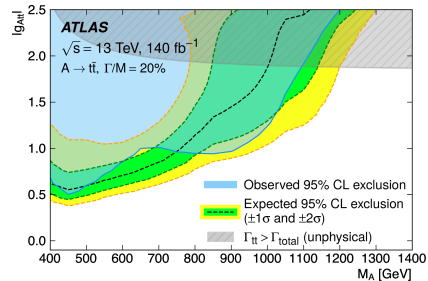
## Measurements

Signal strength quantification



## (Re)interpretations

Theoretical constraints



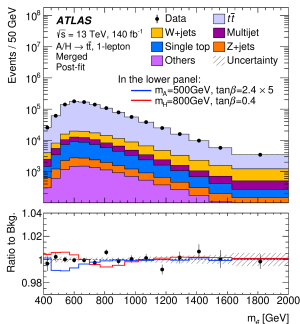
ATLAS-EXOT-2020-25

# New measurement, new analysis?



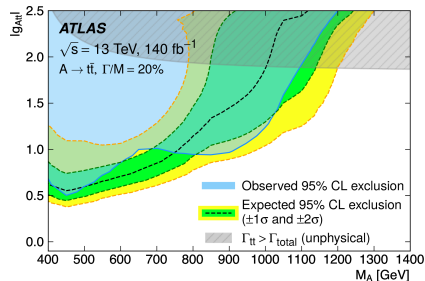
## Measurements

Signal strength quantification



## (Re)interpretations

Theoretical constraints



ATLAS-EXOT-2020-25

Accessible analysis logic → +62% citations [arXiv:2504.00256](https://arxiv.org/abs/2504.00256)

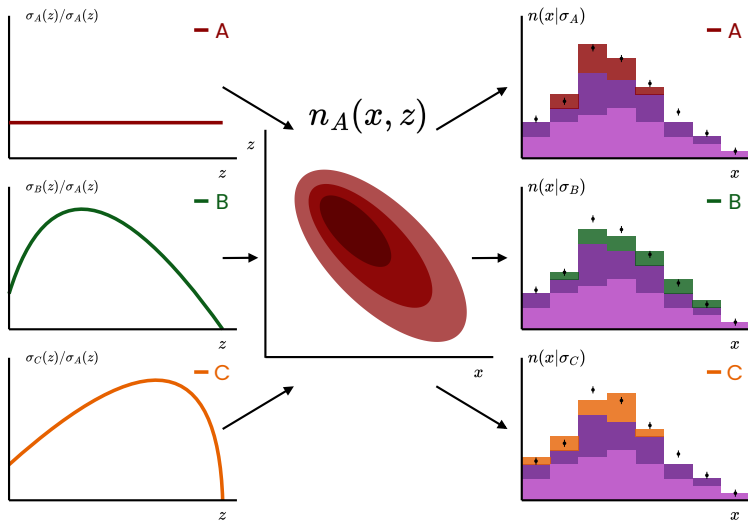


A “novel” reinterpretation framework

EPJC 84, 693 (2024)

[github.com/lorenzennio/redist](https://github.com/lorenzennio/redist)

# Templates from kinematic distributions



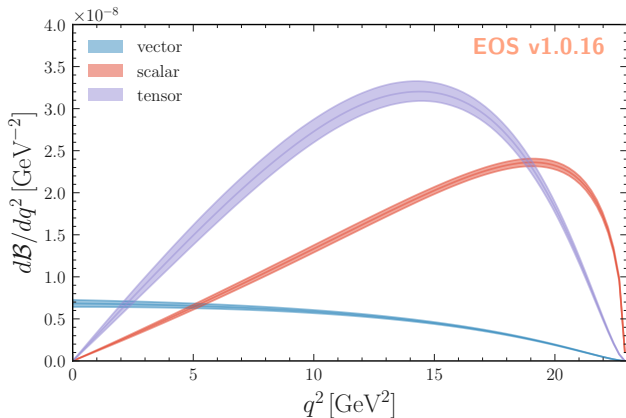
# Constraining $b \rightarrow s\nu\nu$ weak effective field theory (WET) Wilson coefficients

# $b \rightarrow s\nu\nu$ WET decay kinematics



$$\begin{aligned}\frac{d\mathcal{B}}{dq^2} = & \alpha \left| C_{VL} + C_{VR} \right|^2 \\ & + \beta \left| C_{SL} + C_{SR} \right|^2 \\ & + \gamma \left| C_{TL} \right|^2\end{aligned}$$

SM contains only *vector* contribution.



$$q^2 = (p_B - p_K)^2$$

# Validation through closure testing



- Build simple statistical model on MC data
- Inject new physics in MC data
- Infer a posterior in the Wilson coefficients

$$p(\theta|x) \propto p(x|\theta)p(\theta)$$

EPJC 84, 693 (2024)

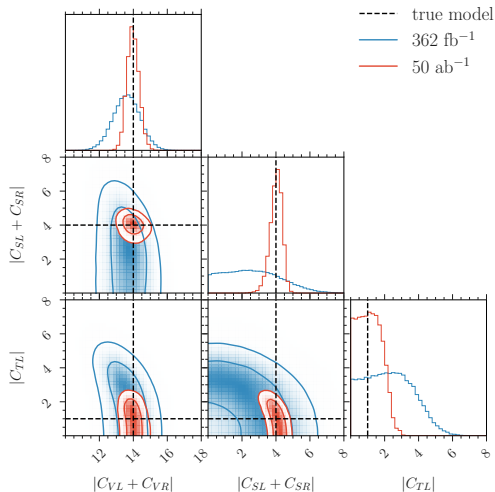
# Validation through closure testing



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EPJC 84, 693 (2024)



# Necessity of reinterpretation



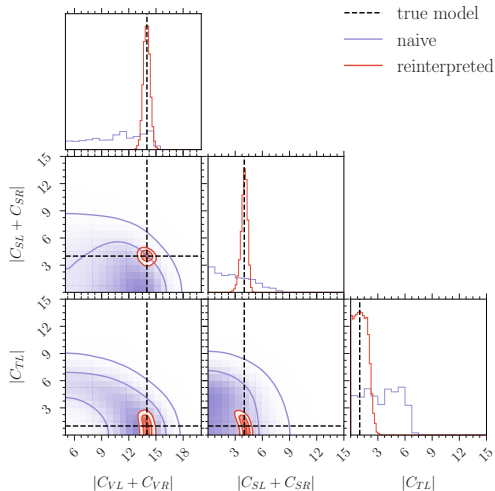
- Infer Wilson coefficients only from

$$\mathcal{B}(\{C_i\})/\mathcal{B}_{SM}$$

- Ignore effect of kinematic shape changes

→ **No constraining power!**

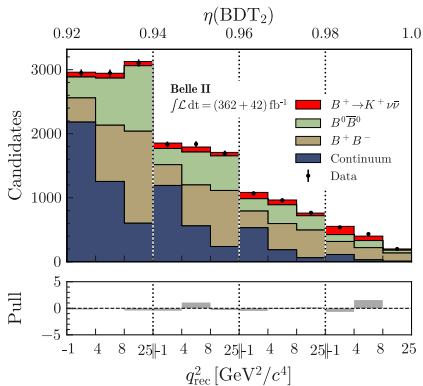
EPJC 84, 693 (2024)



# Belle II has reported

## “Evidence for $B^+ \rightarrow K^+ \nu \bar{\nu}$ decays”

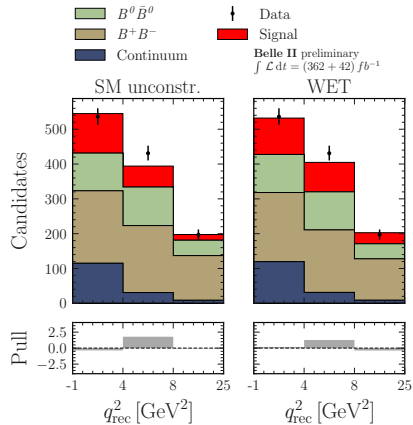
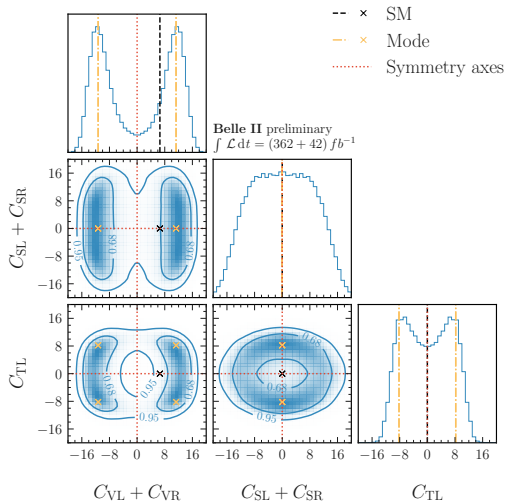
PRD 109.112006



Based on  $p(x|\text{SM})$ .

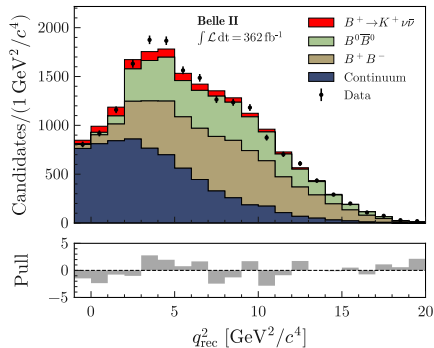
Implications for  $p(x|\text{NP})$ ?

# WET marginal posterior



## Two-body scenarios

Potential  $B^+ \rightarrow K^+ \nu \bar{\nu}$  signal contribution from  
 $B^+ \rightarrow K^+ X$



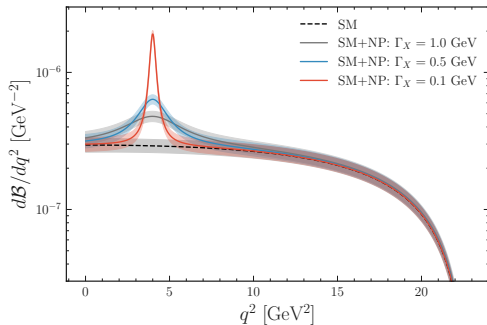
See [arXiv:2311.14629](https://arxiv.org/abs/2311.14629), [arXiv:2312.12507](https://arxiv.org/abs/2312.12507) for initial estimates.

# Decay kinematics

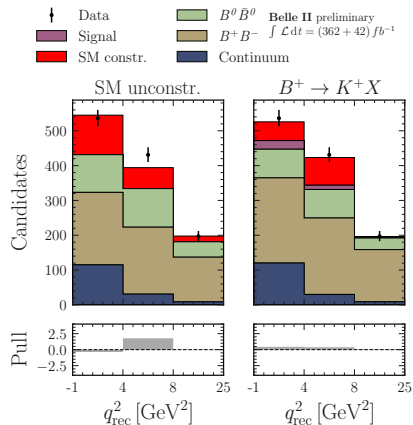
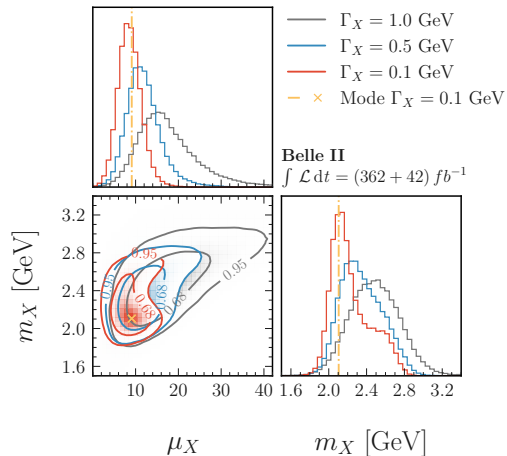


Model as sharp resonance peak,

$$\frac{d\mathcal{B}}{dq^2} = \mu_{SM} \frac{d\mathcal{B}_{SM}}{dq^2} + \mu_X p_{BW}(q^2|m_X, \Gamma_X) \cdot 10^{-6},$$
$$p_{BW}(q^2|m_X, \Gamma_X) = \frac{k}{(q^2 - m_X^2)^2 + m_X^2 \Gamma_X^2}$$



# $B^+ \rightarrow K^+ X$ marginal posterior



# Main takeaways



- ♻️ **Publishable, reinterpretable likelihood** for  $B^+ \rightarrow K^+ \nu \bar{\nu}$ 
  - **Bias-free BSM inference**, reproducibility, combinations, ...
  - Precedent case for future Belle II analyses.
- **WET: first ever** CI for WET WCs, improved fit to data over SM
- $B^+ \rightarrow K^+ X$ : CI for  $m_X, \mu_X$ , best fit to data among tested models
- **NEW**:  $B^0 \rightarrow K^{*0} \tau^+ \tau^-$  reinterp. → Tim Würthner @ poster session

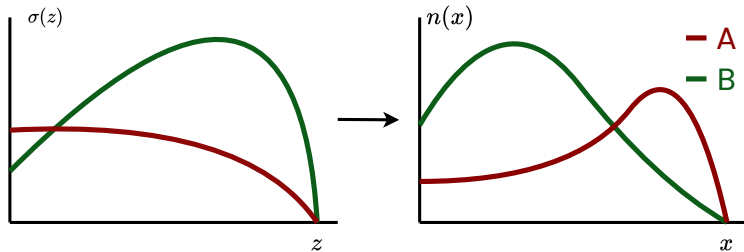
**Reinterpretation enhances analysis impact and reach!**



[arXiv:2507.12393](https://arxiv.org/abs/2507.12393),  
[EPJC 84, 693 \(2024\)](#) /  
[arXiv:2402.08417](https://arxiv.org/abs/2402.08417)

# Templates from kinematic predictions

$$n(x|\sigma) = \int dz L \varepsilon(x|z) \sigma(z) = \int dz n_{\sigma}(x, z)$$



$z(= q^2)$  – kinematic d.o.f.

$x$  – reconstruction / fitting variable(s)

$L$  – luminosity

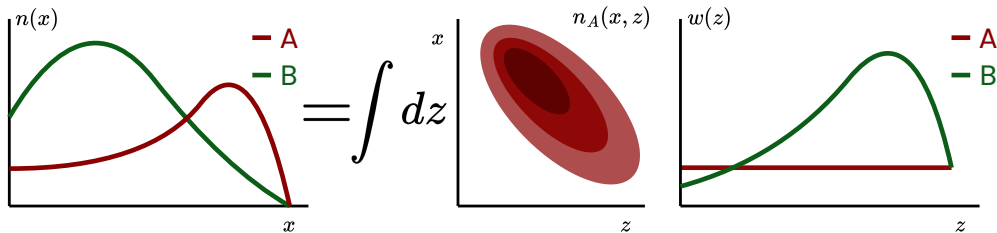
$\varepsilon(x|z)$  – conditional efficiency

$n_{\sigma}(x, z)$  – joint number density

# Reweight to new model



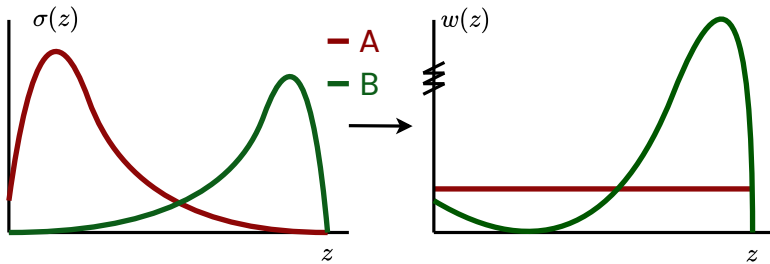
$$n(x|B) = \int dz L \varepsilon(x|z) \sigma_B(z) = \int dz L \varepsilon(x|z) \underbrace{\sigma_A(z)}_{\text{main object}} \frac{\sigma_B(z)}{\sigma_A(z)} = \int dz \underbrace{n_A(x, z)}_{\text{main object}} w(z).$$



$$p(x|n_A, \theta) = \text{model-agnostic likelihood}$$

# Method limitations

Substantial model changes  $\rightarrow$  large weights



Minimal requirement:

$$\text{supp}(\sigma_B) \in \text{supp}(\sigma_A)$$

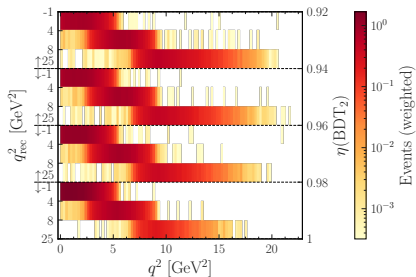
Always possible to compare only in  $\text{supp}(\sigma_A)$

# Joint number densities

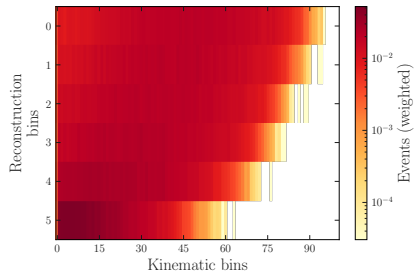


Main object for reinterpretation,  $n(x, z) \rightarrow$  **Essential for publication.**

**ITA** (plot for publication)



**HTA**



Kinematic binning:  $q^2 = [-1, (0, 22.885, 100)] \text{ GeV}^2$

# Weak Effective Theory for $B \rightarrow K \nu \bar{\nu}$



The effective Lagrangian is

$$\mathcal{L}^{WET} = \sum_{X=L,R} C_{VX} \mathcal{O}_{VX} + \sum_{X=L,R} C_{SX} \mathcal{O}_{SX} + C_{TL} \mathcal{O}_{TL} + \text{h.c.}$$

The  $d = 6$  contributing operators in and beyond the SM are given by

$$\begin{aligned} \mathcal{O}_{VL} &= (\bar{\nu}_L \gamma_\mu \nu_L) (\bar{s}_L \gamma^\mu b_L) & \mathcal{O}_{VR} &= (\bar{\nu}_L \gamma_\mu \nu_L) (\bar{s}_R \gamma^\mu b_R) \\ \mathcal{O}_{SL} &= (\bar{\nu}_L^c \nu_L) (\bar{s}_R b_L) & \mathcal{O}_{SR} &= (\bar{\nu}_L^c \nu_L) (\bar{s}_L b_R) \\ \mathcal{O}_{TL} &= (\bar{\nu}_L^c \sigma_{\mu\nu} \nu_L) (\bar{s}_R \sigma^{\mu\nu} b_L) \end{aligned}$$

[arXiv:2111.04327](https://arxiv.org/abs/2111.04327)

# WET decay kinematics



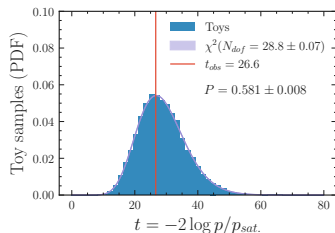
$$\begin{aligned} \frac{d\mathcal{B}(B \rightarrow K \nu \bar{\nu})}{dq^2} = & \frac{3G_F^2 \alpha^2 \tau_B}{32\pi^5 m_B^3} |V_{ts}^* V_{tb}|^2 \sqrt{\lambda_{BK}} q^2 \left[ \frac{\lambda_{BK}}{24q^2} \left| f_+(q^2) \right|^2 \left| C_{VL} + C_{VR} \right|^2 \right. \\ & + \frac{(m_B^2 - m_K^2)^2}{8(m_b - m_s)^2} \left| f_0(q^2) \right|^2 \left| C_{SL} + C_{SR} \right|^2 \\ & \left. + \frac{2\lambda_{BK}}{3(m_B + m_K)^2} \left| f_T(q^2) \right|^2 \left| C_{TL} \right|^2 \right] \end{aligned}$$

for  $J^P = 0^-$  kaon states.  
Note  $q^2 \neq q_{rec}^2$ .

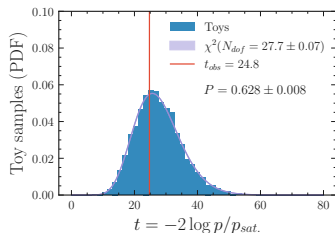
arXiv:2111.04327

$$P_{\text{gof}} = \int_{t_{\text{obs}}}^{\infty} dt p(t, \quad t = -2 \ln \frac{p(n, a | \hat{\eta}, \hat{\chi})}{p_{\text{sat}}(n, a | \bar{\chi})},$$

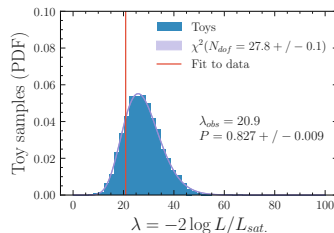
SM



WET



$B^+ \rightarrow K^+ X$



# Averaged: Bayes factor

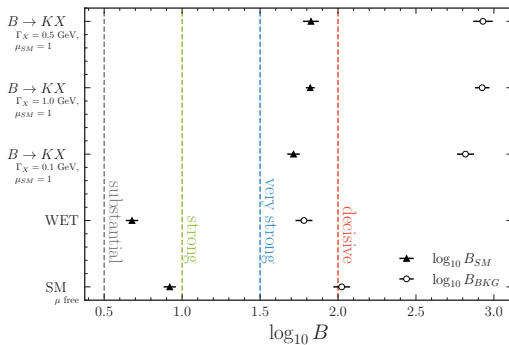


Compare the probabilities of the observed data being produced by a given model.

$$B_M = \frac{p(x|M')}{p(x|M)}$$

$$p(x|M) = \int d^n\theta p(x|\theta, M) p(\theta|M)$$

→  $B^+ \rightarrow K^+ X$  models dominate over SM and WET.

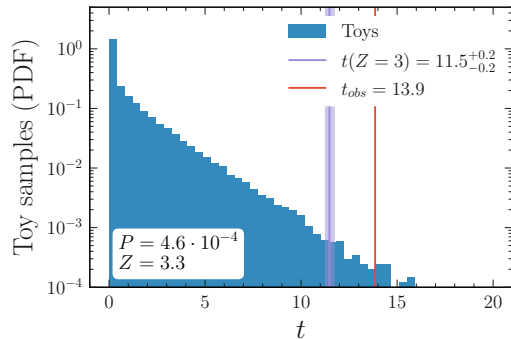


# Pointwise: P-value

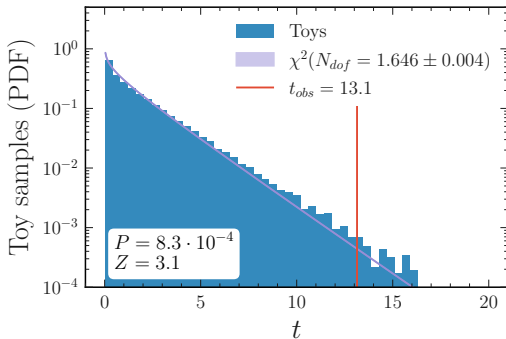


$$P = \int_{t_{\text{obs}}}^{\infty} dt p(t), \quad t = -2 \ln \frac{p(n, a \mid \eta = 0, \hat{\chi})}{p(n, a \mid \hat{\eta}, \hat{\chi})},$$

WET vs. BKG



$B^+ \rightarrow K^+ X$  vs. SM+BKG



## Alternative priors

$$p(\eta_i) = \begin{cases} \mathcal{N}(\eta_i | \mu = C_i^{\text{SM}}, \sigma = 20) & \eta_i \geq 0 \\ 0 & \eta_i < 0 \end{cases} \quad (1)$$

$$p(\eta_i) \propto \begin{cases} \eta_i & \eta_i \leq 30 \\ 0 & \eta_i > 30 \end{cases} \quad (2)$$

### Uniform priors

| Parameters                        | Mode | 68% HDI      | 95% HDI      |
|-----------------------------------|------|--------------|--------------|
| $ C_{\text{VL}} + C_{\text{VR}} $ | 11.3 | [7.82, 14.6] | [1.86, 16.2] |
| $ C_{\text{SL}} + C_{\text{SR}} $ | 0.00 | [0.00, 9.53] | [0.00, 15.4] |
| $ C_{\text{TL}} $                 | 8.21 | [2.29, 9.62] | [0.00, 11.2] |

### Alternative priors

| Priors | Parameters                        | Mode | 68% HDI      | 95% HDI      |
|--------|-----------------------------------|------|--------------|--------------|
| (1)    | $ C_{\text{VL}} + C_{\text{VR}} $ | 11.4 | [7.97, 14.6] | [2.21, 16.4] |
|        | $ C_{\text{SL}} + C_{\text{SR}} $ | 0.00 | [0.00, 9.16] | [0.00, 14.7] |
|        | $ C_{\text{TL}} $                 | 7.69 | [1.54, 8.75] | [0.00, 11.0] |
| (2)    | $ C_{\text{VL}} + C_{\text{VR}} $ | 11.6 | [8.21, 14.0] | [4.17, 16.0] |
|        | $ C_{\text{SL}} + C_{\text{SR}} $ | 8.93 | [4.56, 12.6] | [1.27, 15.6] |
|        | $ C_{\text{TL}} $                 | 7.17 | [3.89, 9.59] | [1.41, 11.7] |

## Alternative priors

$$p(\mu_X) = \begin{cases} \mathcal{N}(\mu_X | \mu = 0, \sigma = 20) & \mu_X \geq 0 \\ 0 & \mu_X < 0 \end{cases}, \quad (3)$$

$$p(m_X) = \mathcal{U}([1.5, 3.0] \text{ GeV})$$

$$p(\mu_X) = \mathcal{U}([0, 24]),$$

$$p(m_X) \propto \begin{cases} m_X & m_X \leq 4.8 \text{ GeV} \\ 0 & m_X > 4.8 \text{ GeV} \end{cases} \quad (4)$$

### Uniform priors

| Param.      | Mode | 68% HDI      | 95% HDI      |
|-------------|------|--------------|--------------|
| $\mu_X$     | 9.15 | [5.75, 11.0] | [3.44, 14.0] |
| $m_X$ [GeV] | 2.11 | [1.96, 2.33] | [1.92, 2.69] |

### Alternative priors

| Priors | Param.      | Mode | 68% HDI      | 95% HDI      |
|--------|-------------|------|--------------|--------------|
| (3)    | $\mu_X$     | 9.00 | [5.67, 10.8] | [3.41, 13.8] |
|        | $m_X$ [GeV] | 2.12 | [1.97, 2.35] | [1.92, 2.69] |
| (4)    | $\mu_X$     | 9.04 | [5.72, 11.0] | [2.99, 14.4] |
|        | $m_X$ [GeV] | 2.11 | [1.97, 2.39] | [1.92, 2.74] |

# A comparative scale



## Naive reinterpretation

For each Wilson coefficient

$$\mu_{SM} \mathcal{B}_{SM} = \int dq^2 \frac{d\mathcal{B}_{WET}}{dq^2}$$

$$|C_{VL} + C_{VR}| = 14.2^{+1.9}_{-2.2}$$

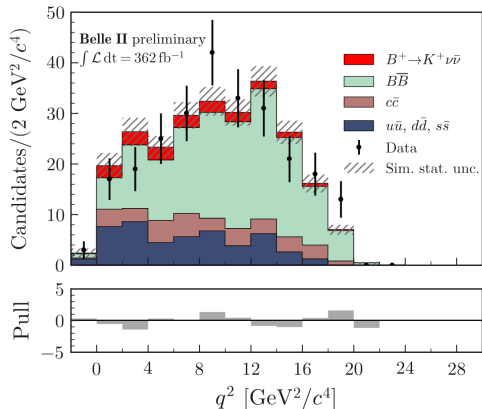
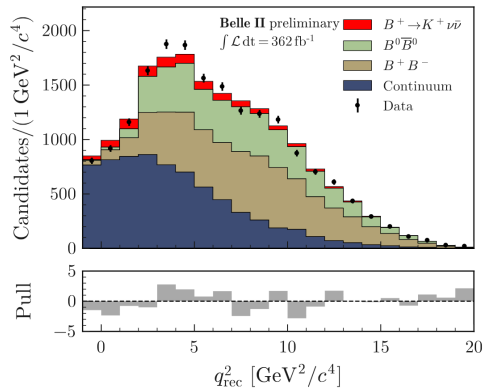
$$|C_{SL} + C_{SR}| = 8.38^{+1.12}_{-1.30}$$

$$|C_{TL}| = 6.93^{+0.93}_{-1.08}$$

## Our results

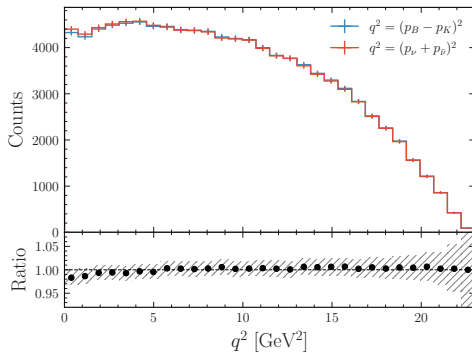
| Parameters          | Mode | 68% HDI      |
|---------------------|------|--------------|
| $ C_{VL} + C_{VR} $ | 11.3 | [7.82, 14.6] |
| $ C_{SL} + C_{SR} $ | 0.00 | [0.00, 9.53] |
| $ C_{TL} $          | 8.21 | [2.29, 9.62] |

# Motivation for $B \rightarrow KX$



Excess around  $3 \text{ GeV}^2 < q_{\text{rec}}^2 < 7 \text{ GeV}^2$  for ITA best-fit projection.

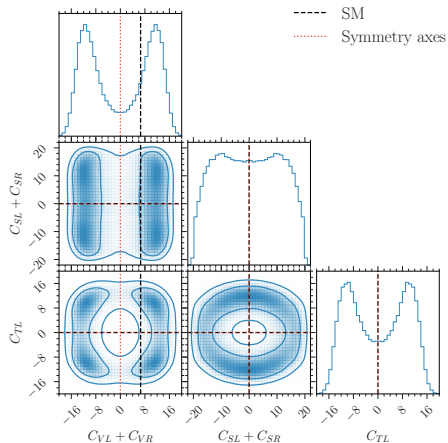
# Final state radiation



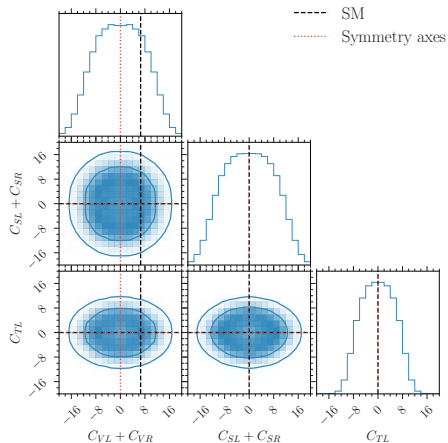
# WET marginal posteriors (individual)



ITA



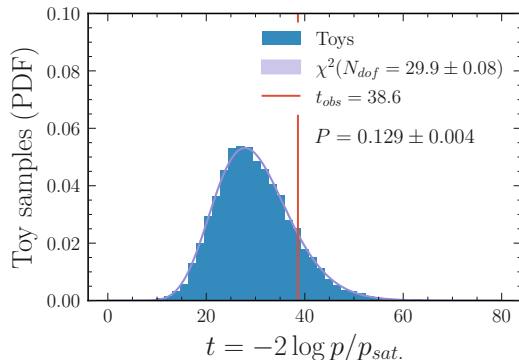
HTA



# Goodness of fit: background only



$$P_{gof} = \int_{\lambda_{obs}}^{\infty} d\lambda p(\lambda) = 1 - CDF_p(\lambda_{obs}),$$



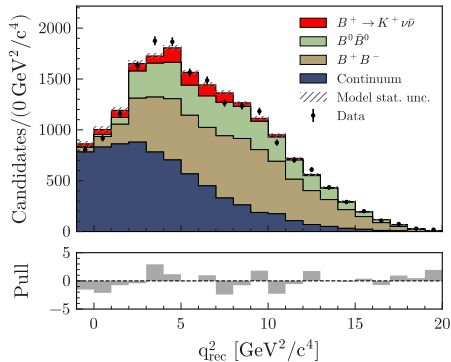
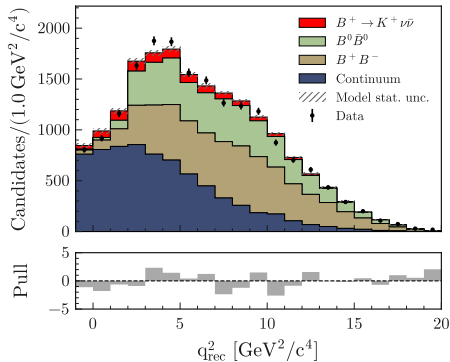
Test statistic PDF,  $p(\lambda)$ , from toy study, 10k toys

# $q_{rec}^2$ projections



WET

$B \rightarrow KX$



Since the  $q_{rec}^2$  resolution of the reconstruction

Likelihood function for observed event counts  $n$  is

$$L(n, a|\eta, \chi) = \underbrace{\prod_{c \in \text{channels}} \prod_{b \in \text{bins}} \text{Pois}(n_{cb}|\nu_{cb}(\eta, \chi))}_{\text{multiple channels}} \underbrace{\prod_{\chi \in \chi} c_{\chi}(a_{\chi}|\chi)}_{\text{constraint terms}}$$

Expected number of events per channel per bin are

$$\nu_{cb}(\eta, \chi) = \sum_{s \in \text{samples}} \underbrace{\prod_{\kappa \in \kappa} \kappa_{scb}(\eta, \chi)}_{\text{multiplicative modifiers}} (\nu_{scb}^0(\eta, \chi) + \underbrace{\sum_{\Delta \in \Delta} \Delta_{scb}(\eta, \chi)}_{\text{additive modifiers}}).$$

# Modifiers and constraints



| Description          | Modification                                                                         | Constraint Term $c_\chi$                                                     | Input                               |
|----------------------|--------------------------------------------------------------------------------------|------------------------------------------------------------------------------|-------------------------------------|
| Uncorrelated Shape   | $\kappa_{scb}(\gamma_b) = \gamma_b$                                                  | $\prod_b \text{Pois}(r_b = \sigma_b^{-2}   \rho_b = \sigma_b^{-2} \gamma_b)$ | $\sigma_b$                          |
| Correlated Shape     | $\Delta_{scb}(\alpha) = f_p(\alpha   \Delta_{scb,\alpha=-1}, \Delta_{scb,\alpha=1})$ | $\text{Gaus}(a = 0   \alpha, \sigma = 1)$                                    | $\Delta_{scb,\alpha=\pm 1}$         |
| Normalisation Unc.   | $\kappa_{scb}(\alpha) = g_p(\alpha   \kappa_{scb,\alpha=-1}, \kappa_{scb,\alpha=1})$ | $\text{Gaus}(a = 0   \alpha, \sigma = 1)$                                    | $\kappa_{scb,\alpha=\pm 1}$         |
| MC Stat. Uncertainty | $\kappa_{scb}(\gamma_b) = \gamma_b$                                                  | $\prod_b \text{Gaus}(a_{\gamma_b} = 1   \gamma_b, \delta_b)$                 | $\delta_b^2 = \sum_s \delta_{sb}^2$ |
| Luminosity           | $\kappa_{scb}(\lambda) = \lambda$                                                    | $\text{Gaus}(l = \lambda_0   \lambda, \sigma_\lambda)$                       | $\lambda_0, \sigma_\lambda$         |
| Normalisation        | $\kappa_{scb}(\mu_b) = \mu_b$                                                        |                                                                              |                                     |
| Data-driven Shape    | $\kappa_{scb}(\gamma_b) = \gamma_b$                                                  |                                                                              |                                     |

# Custom modifiers

