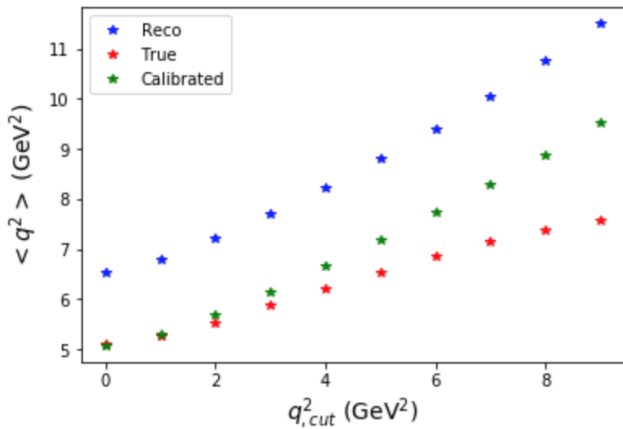
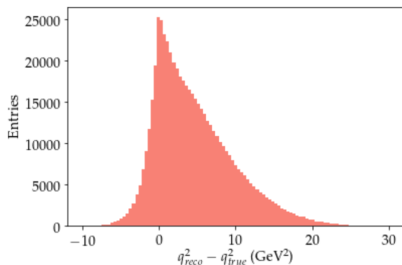


????????????????????

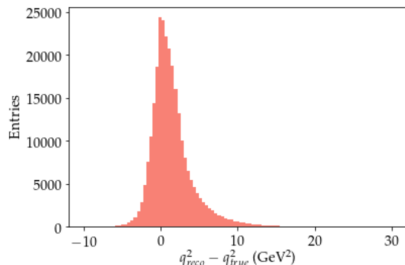


q^2 resolution

The $|E_{miss} - p_{miss}| < 0.5$ GeV selection requirement greatly improves the resolution:



Resolution before cut



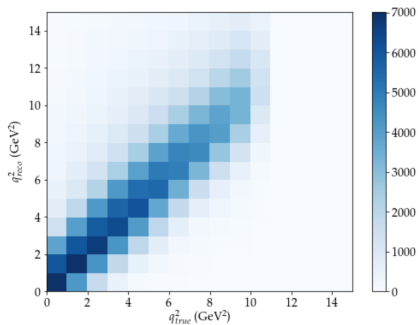
Resolution after cut

Me: the resolution looks so much better now!

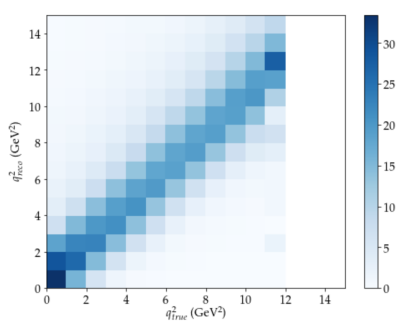
Christoph: still looks really bad.

Me: oh. :-)

Migration matrix



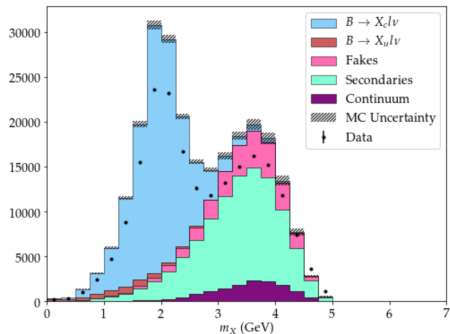
Before normalizing



Normalized to percentage

Secondary correction

Use a secondary enriched region to estimate a secondary shape correction function:

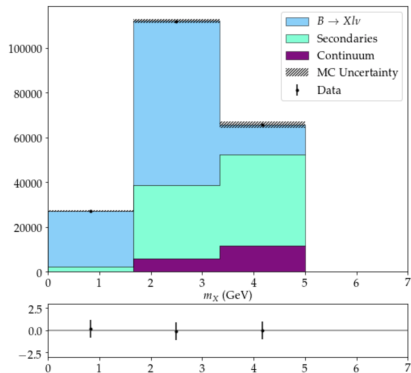


Secondary selection

- $m_{bc} > 5.27$ GeV
- $\log(\text{NB}) > -4$
- $\log(\text{contNB}) > -4$
- $p_e > 0.3$
- $p_\mu > 0.6$
- $Q_{\text{tag}} \times Q_{\text{lep}} > 0$
- $|E_{\text{miss}} - p_{\text{miss}}| < 0.5$

Secondary correction

Use a secondary enriched region to estimate a secondary shape correction function:

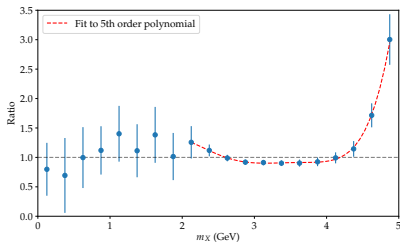
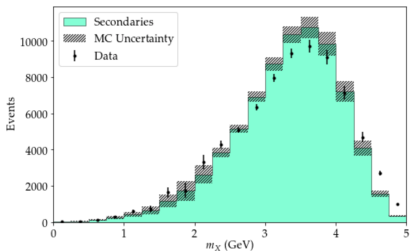


- Fit m_X in coarse bins to determine $B \rightarrow X l \nu$ component
- Use these normalizations to subtract the m_X distribution in fine bins
- Derive a correction function from the secondary versus subtracted shape

Christoph: why are you doing something so complicated?

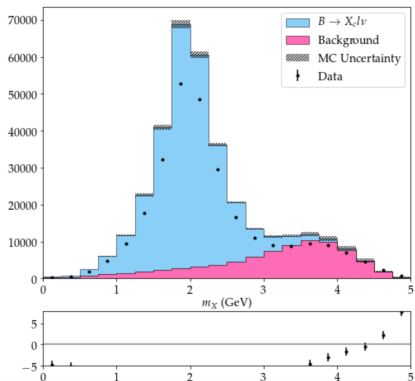
Secondary correction

Use a secondary enriched region to estimate a secondary shape correction function:

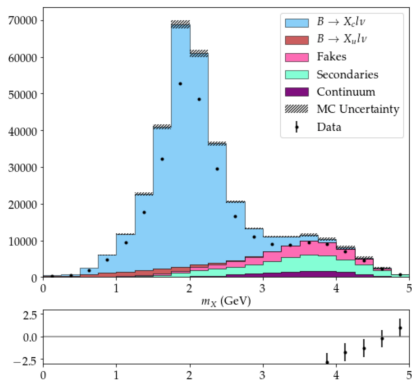


- Derive a correction function from the ratio between the secondary shape and subtracted data.

Corrected m_X distribution



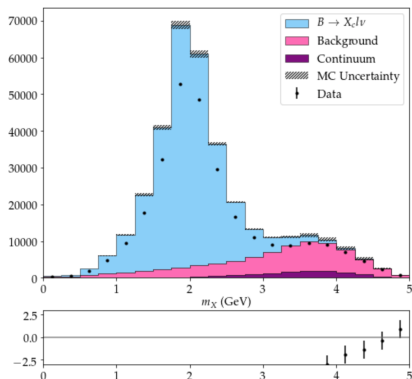
Before



After

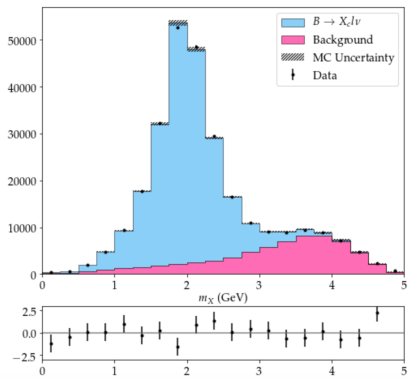
Fit with corrected m_X distribution

Estimate background component from a three component template fit to m_X

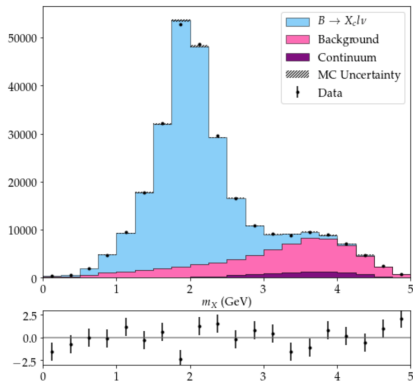


- Templates constrained to $X_c l \nu$ BF errors (PDG 2020)
- All MC correction errors included as nuisance parameters
- 100% uncertainty assigned to the Gap modes
- Continuum constrained to off-resonance expectation

Fit results

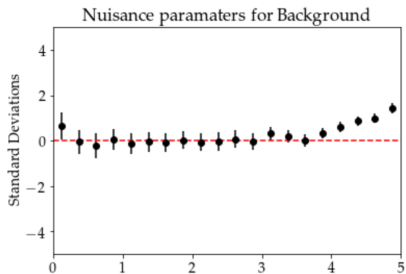
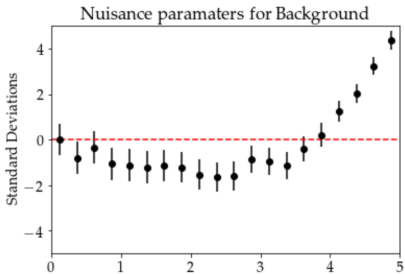


Old



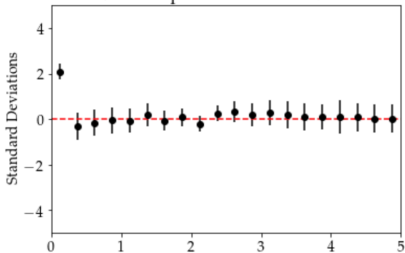
New

Nuisance parameters

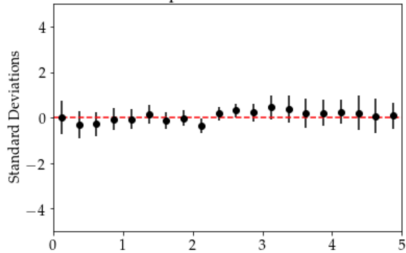


Nuisance parameters

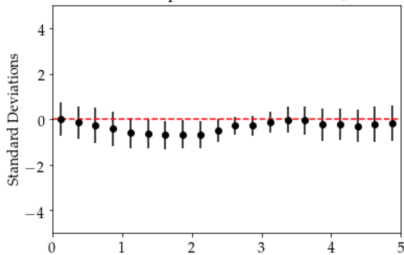
Nuisance parameters for $B \rightarrow D l \nu$



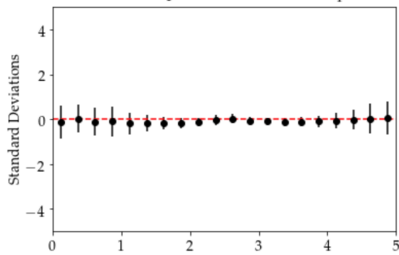
Nuisance parameters for $B \rightarrow D^* l \nu$



Nuisance parameters for $B \rightarrow D_1 l \nu$

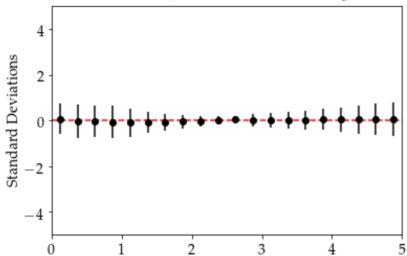


Nuisance parameters for $B \rightarrow D'_1 l \nu$

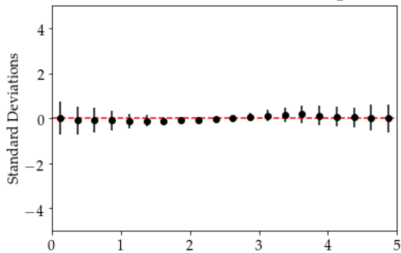


Nuisance parameters

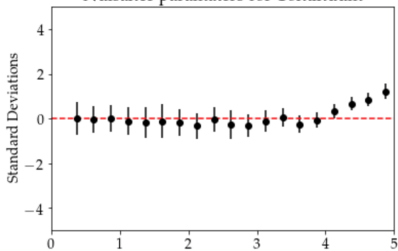
Nuisance parameters for $B \rightarrow D_0^* l \nu$



Nuisance parameters for $B \rightarrow D_2^* l \nu$

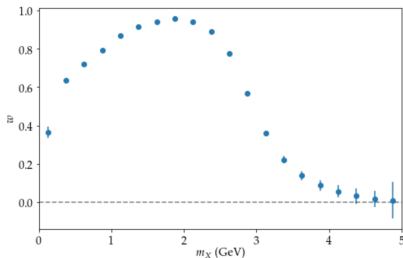
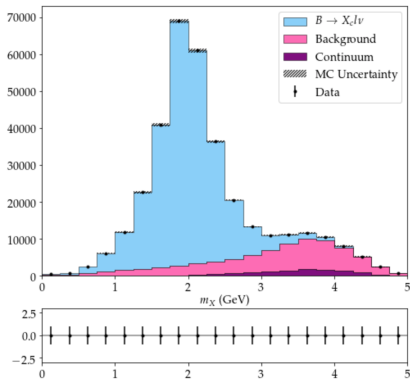


Nuisance parameters for Continuum



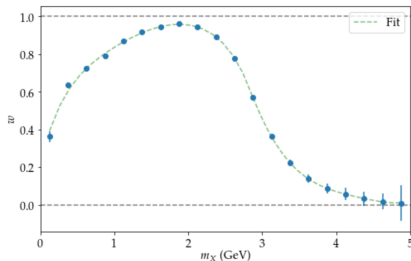
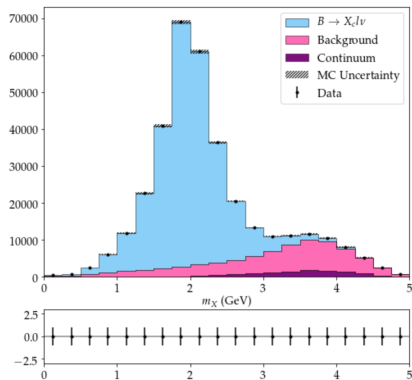
Calculating w_i

Calculate $w(m_X) = 1 - N_{bkg}/N_{tot}$ for each bin (only with MC for now):



Calculating w_i

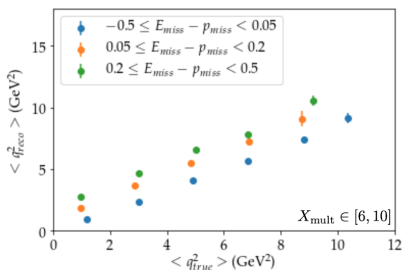
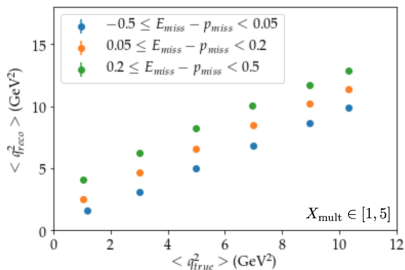
Calculate $w(m_X) = 1 - N_{bkg}/N_{tot}$ for each bin (only with MC for now):



- Here, I fitted 2 polynomials over different ranges

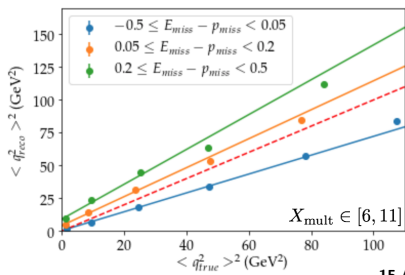
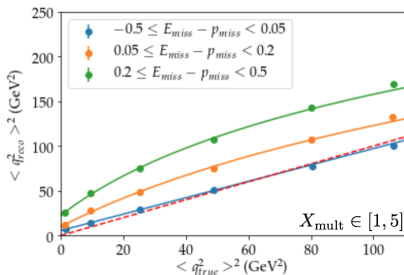
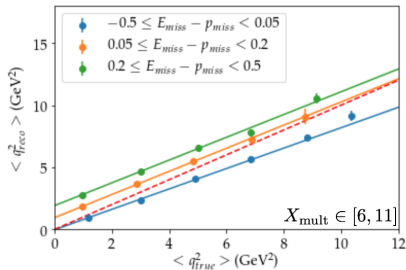
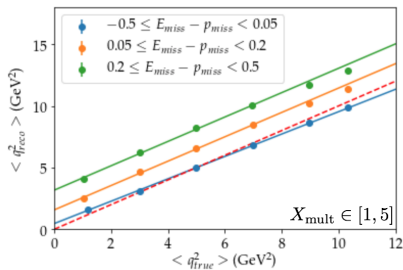
Calibration

- Determine $\langle q_{\text{reco}}^2 \rangle$ and $\langle q_{\text{true}}^2 \rangle$ in bins of q_{true}^2
- We see a linear behaviour between $\langle q_{\text{reco}}^2 \rangle$ and $\langle q_{\text{true}}^2 \rangle$
- Fit in bins of X_{mult} and $E_{\text{miss}} - p_{\text{miss}}$
 - Three bins in $E_{\text{miss}} - p_{\text{miss}}$: [-0.5, 0.05, 0.2, 0.5] GeV
 - Two bins in X_{mult} : [1, 5] and [6, 10]
- Calculate $q_{\text{calib}}^2 = (q_{\text{reco}}^2 - c)/m$



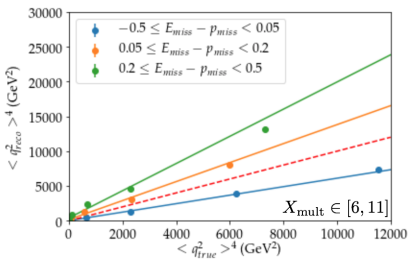
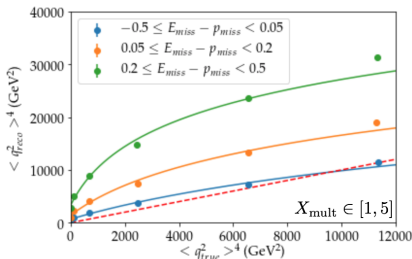
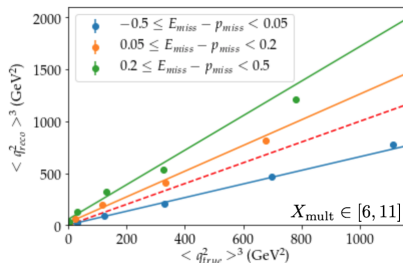
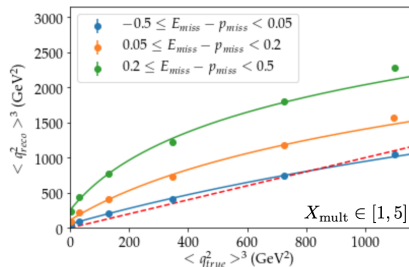
Fit to extract the calibration

Fit linear curves to each of the scatter plots:



Fit to extract the calibration

Fit linear curves to each of the scatter plots:

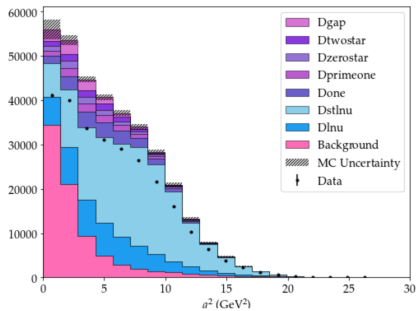
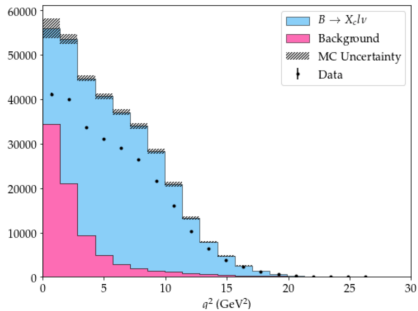


- Finish deriving the correction function for the secondaries (check!)
- Redo the m_X fit with the shape correction factors from the secondary enriched sample (check!)
- Determine the event-wise signal probability as a function of m_X (check!)
- Study and refine the calibration steps a bit more (check!)
- Investigate the additional bias correction, C_{calib} (Working on it!)
- Bonus Round: Get MC closure (Almost done!)

Next steps, questions, discussion points

- Finish getting MC closure
- Investigate the additional bias correction, $\mathcal{C}_{\text{calib}}$
- Propagate uncertainties through all the analysis steps
- Decide the width that we will use to present the final results
- Write my Belle Note (/thesis) when I'm bored (FYI: already started)

q^2 distribution after selection and corrections



How to calculate moments

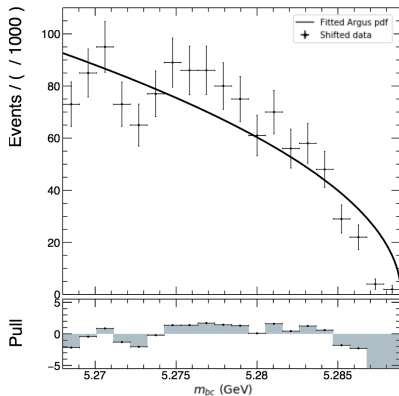
Moments calculated as a weighted mean:

$$\langle q^2 \rangle_n = \frac{\sum w_i(q^2) (q_{\text{calib},i}^2)^n}{\sum_i w_i(q^2)} \times \mathcal{C}_{\text{calib}}$$

- $w_i(q^2)$: Event-wise signal probability as a function of q^2
- $q_{\text{calib},i}^2$: Calibrated q_{reco}^2
- $\mathcal{C}_{\text{calib}}$: Additional bias correction

Continuum correction

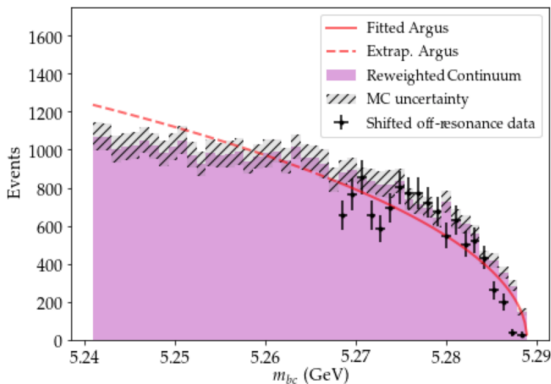
Use off-resonance data to derive a correction factor for Continuum MC



- Apply nominal selection cuts
- Shift data to end point of the distribution
- Fit Argus function to data points
- Extrapolate to full m_{bc} range

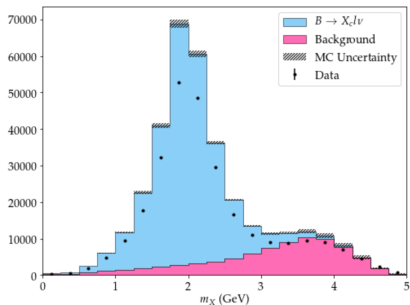
Continuum correction

Weight the number of MC to the number of expected events from the fit result:



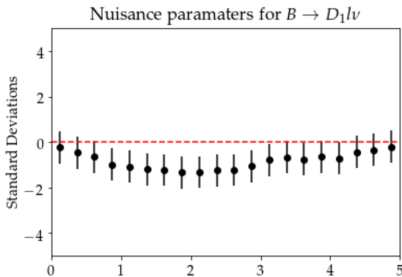
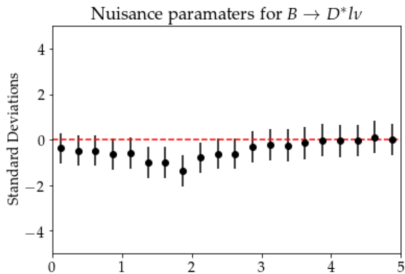
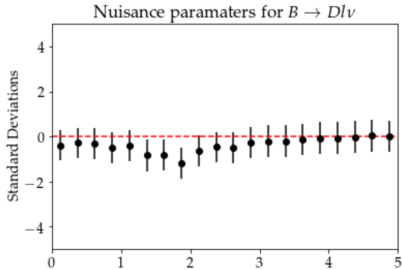
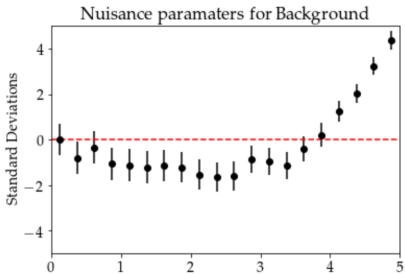
Old background subtraction

Estimate background component from a two component template fit to m_X



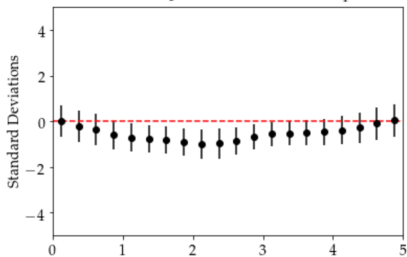
- Templates constrained to $X_c l \nu$ BF errors (PDG 2020)
- All MC correction errors included as nuisance parameters
- Tracking error
- 100% uncertainty assigned to the Gap modes

Old nuisance parameters

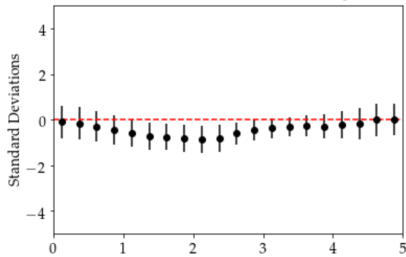


Old nuisance parameters

Nuisance parameters for $B \rightarrow D'_1 l \nu$



Nuisance parameters for $B \rightarrow D'_0 l \nu$



Old nuisance parameters

