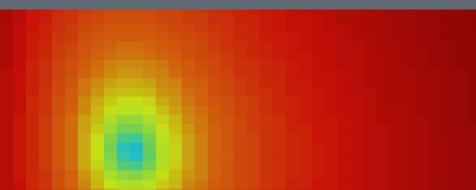
Theory perspective on Data Preservation: Experimental data in Flavio

Peter Stangl CERN



flavio: what can it do for me?

https://github.com/flav-io/flavio D. Straub.arXiv:1810.08132



1. Computing theory predictions

for a large number of observables (flavour physics, electroweak precision observables, Higgs physics, ...)

- Standard Model (SM) predictions
- Predictions in the presence of **new physics** (NP) (parameterized by Wilson coefficients)
- Theory uncertainties for SM and NP



2. Database of experimental measurements

for all implemented observables that have been measured

- provided in terms of YAML file
- easy to update and extend

 \rightarrow more on this later!



3. Likelihoods

Combining predictions with experimental data allows constructing likelihoods

- Likelihoods in parameters (e.g. CKM parameters) or Wilson coefficients
- Possibility to use Gaussian approximation for fast likelihood estimates
- Use external fitters to perform Bayesian or frequentist statistics with flavio likelihoods
- Basis for the smelli global SMEFT LikeLIhood Python package

https://github.com/smelli/smelli Aebischer, Kumar, PS, Straub, arXiv:1810.07698 PS, arXiv:2012.12211

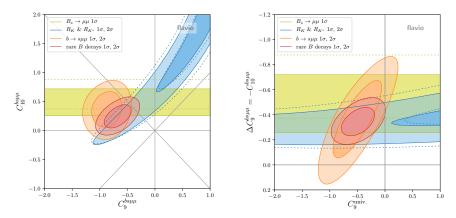


4. Plots

- Visualize experimental measurements & theory predictions
- Visualize your likelihoods

😽 flavio: showcase

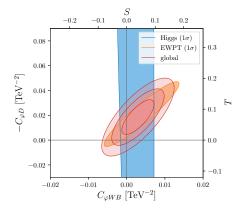
New physics in B-decays in Weak effective theory Wilson coefficients @ 4.8 GeV



Altmannshofer, PS, arXiv:2103.13370



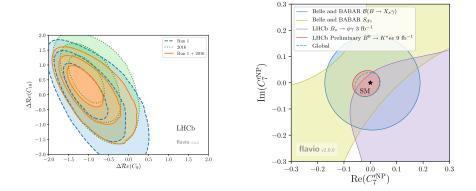
S-T fit using combined Higgs and electroweak likelihood in SMEFT



Falkowski, Straub, arXiv:1911.07866

😽 flavio: showcase

Fits to new physics Wilson coefficients from recent LHCb analyses



LHCb-PAPER-2020-002 LHCb-TALK-2020-155

- A measurement in flavio corresponds to a likelihood associated with one (or more) observable(s)
- The likelihood is provided by experiments and included in flavio
- Predefined measurements contained in file measurements.yaml
- Simple example in flavio YAML format:

- The constraint is interpreted as Gaussian likelihood
- Different error contributions are summed in quadrature

Observables can have asymmetric uncertainties

1	K+->pinunu NA62 2019:	#	name
2	experiment: NA62	#	experiment
3	values:		
4	BR(K+->pinunu): 0.47 + 0.72 - 0.47 e-10	#	constraint

The constraint is interpreted as combination of two half Gaussians

For measurement of correlated observables, the correlation can be specified

```
      1
      Belle RD* sl 2019:
      # name

      2
      experiment: Belle
      # experiment

      3
      inspire: Abdesselam:2019dgh
      # INSPIRE tex key

      4
      values:
      5

      5
      Rtaul(B->Dlnu): 0.307 ± 0.037 ± 0.016
      # constraint observable 1

      6
      Rtaul(B->D*lnu): 0.283 ± 0.018 ± 0.014
      # constraint observable 2

      7
      correlation: -0.53
      # correlation
```

- The constraints are interpreted as 2D Gaussian likelihood
- Different error contributions are summed in quadrature

For more than two correlated observables, the correlation matrix can be specified (in quadratic or triangular form)

```
A 1 SLD:
                                                            # name
    experiment: SLD
                                                            # experiment
     inspire: ALEPH:2005ab
                                                           # INSPIRE tex key
     description: Table 3.6 of arXiv:hep-ex/0509008
                                                           # description
Δ
     values:
       A(Z \rightarrow ee): 0.1516 \pm 0.0021
                                                   # constraint observable 1
    A(Z \rightarrow mumu): 0.142 \pm 0.015
                                              # constraint observable 2
8
       A(Z \rightarrow tautau): 0.136 \pm 0.015
                                                   # constraint observable 2
     correlation: [[1.0, 0.038, 0.033], [1.0, 0.007], [1.0]]#corr.matrix
9
```

The constraints are interpreted as 3D Gaussian likelihood

Simple upper limits on positive quantities can be specified

```
      1
      Belle B->K*emu 2018:
      # name

      2
      experiment: Belle
      # experiment

      3
      inspire: Sandilya:2018pop
      # INSPIRE tex key

      4
      values:
      5

      5
      BR(B0->K*emu): < 1.2e-7 @ 90% CL</td>
      # constraint observable 1

      6
      BR(B0->K*mue): < 1.6e-7 @ 90% CL</td>
      # constraint observable 2
```

The constraints are interpreted as half Gaussians with mode at 0 and cumulative probability below the limit being 0.90 (in this example)

More appropriate upper limit likelihood for low-statistics counting experiments if number of events is available

```
DELPHT Z LEV:
                                                 name
                                               #
2
     experiment: DELPHI
                                               # experiment
     inspire: Abreu:1996mj
                                                INSPIRE tex kev
     values:
Δ
       BR(Z \rightarrow mutau):
                                               # constraint
          distribution: gamma_upper_limit
                                               # type of distribution
         limit: 1.2e-5
         confidence_level: 0.95
8
         counts total: 0
9
          counts_background: 0
```

The constraint is implemented as a Gamma distribution

If number of expected background events is uncertain, background uncertainty can be specified

```
Belle B->hnunu SL 2017:
                                                     #
                                                      name
2
     experiment: Belle
                                                     # experiment
     inspire: Grygier:2017tzo
                                                     # INSPIRE tex kev
     values:
       BR (BO - >K * nunu):
                                                     # constraint
         distribution: general_gamma_upper_limit
                                                     # type of distribution
         limit: 1.8e-5
         confidence level: 0.9
8
         counts total: 13
9
         counts_signal: -2.0
         background_uncertainty: 1.8
```

The constraint is implemented as a Gamma distribution convoluted with a (folded) Gaussian for the background uncertainty

Arbitrary non-Gaussian likelihoods can be given in numerical form

```
LHCb RK 2021:
    experiment: LHCb
     url: http://moriond.in2p3.fr/2021/EW/slides/3_flavour_02_moise.pdf
3
    values:
4
       - name: <Rmue>(B+->Kll)
                                    # constraint for binned observable
         g2min: 1.1
                                    # lower bin boundary
6
         g2max: 6.0
                                    # upper bin boundary
         value:
8
           distribution: numerical # type of distribution
9
10
           x: [0.55, 0.56, 0.57, 0.58, 0.59, 0.60, 0.61, 0.62, ...]
           v: [4.592421315031857e-16, 5.5901132147031404e-15, ...]
```

- y value of the likelihood with arbitrary normalisation
- number of points should not be too small as likelihood is interpolated only linearly between them
- likelihood is assumed to be zero outside of provided range, so range must be large enough, including possible tails

Numerical likelihoods can be specified in arbitrary number of dimensions, e.g.

```
LHCb Bs \rightarrow mumu 2021:
2
     experiment: LHCb
     url: http://moriond.in2p3.fr/2021/EW/slides/3 flavour 01 archilli.
3
          pdf
     observables:
4
       - BR(Bs->mumu)
5
6
       - BR(B0->mumu)
     values:
       distribution: multivariate numerical
8
       xi: [[8.161097450987314e-10, 9.172370129183739e-10, ...],
9
             [-4.806317281473294e-13, 1.2345785573114215e-11, ... ]]
10
       v: [[1.3143971288076154e-07, 1.6755574140528865e-07, ...],
            [3.878158386282714e-07, 4.923565057071156e-07, ...],
            [1.2014436902795998e-06, 1.5185447893919208e-06, ...].
            [3.5512584579519983e-06, 4.468647340339764e-06. ... ].
14
15
            [1.1380897209303134e-06, 1.1676827880277567e-06, ... ]]
16
```

- N dimensional grid given by xi values (here 2D)
- y provides value of the likelihood on the grid as N-dim array

Approximations used for likelihoods

Gaussian likelihoods

- Central values and uncertainties
 - have to be approximated as Gaussian
 - correlations have to be neglected
- Central values and uncertainties + correlations
 - multivariate Gaussian
 - often good approximation close to central values
 - deviations from Gaussian have to be neglected

Upper limits

- Upper limit with confidence level
 - can be approximated as Half-Gaussian
 - not necessarily a good approximation
- Upper limit with confidence level + event counts
 - can be modelled by Gamma distribution
 - more appropriate than Half-Gaussian for low-statistics counting experiment
- Upper limit with confidence level + event counts + background uncertainty
 - can be modelled by Gamma distribution convoluted with (folded) Gaussian

Generic non-Gaussian likelihoods

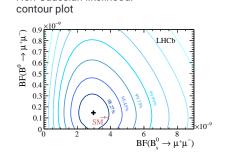
- Likelihoods in parameterized functional form
 - e.g. (convolutions of) parameterized probability distributions
 - can be stored in relatively compact way
- Numerical likelihoods on a grid
 - precision can be increased by finer grid
 - might require large amounts of data to be stored
- Samples from the likelihood distribution
 - precision can be increased by larger number of samples
 - might require large amounts of data to be stored
- New ideas?
 - Neural Networks trained to represent a likelihood

Most simple result: uncorrelated central values and uncertainties

- Most simple result: uncorrelated central values and uncertainties
- More information: correlation between BR($B_d \rightarrow \mu\mu$) and BR($B_s \rightarrow \mu\mu$)

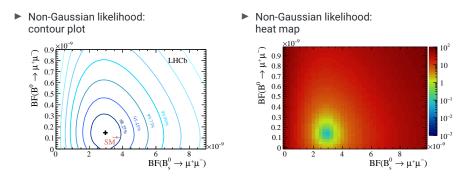
Non-Gaussian likelihood:

- Most simple result: uncorrelated central values and uncertainties
- More information: correlation between BR($B_d \rightarrow \mu\mu$) and BR($B_s \rightarrow \mu\mu$)

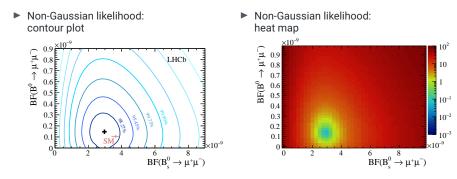


►

- Most simple result: uncorrelated central values and uncertainties
- More information: correlation between BR($B_d \rightarrow \mu\mu$) and BR($B_s \rightarrow \mu\mu$)



- Most simple result: uncorrelated central values and uncertainties
- ▶ More information: correlation between $BR(B_d \rightarrow \mu\mu)$ and $BR(B_s \rightarrow \mu\mu)$



Even better: numerical data instead of only plots!

Wishlist

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- Correlation matrices for measurements of correlated observables
- Event counts (and background uncertainties) for upper limits
- Likelihoods in parameterized functional form (e.g. parameterized Gamma distribution, convolutions of different parameterized distributions, etc.)
- Full non-Gaussian likelihoods
- Likelihoods in numerical form instead of only plots!
- Data files instead of only tables in PDF files!

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Thank you!

Backup slides