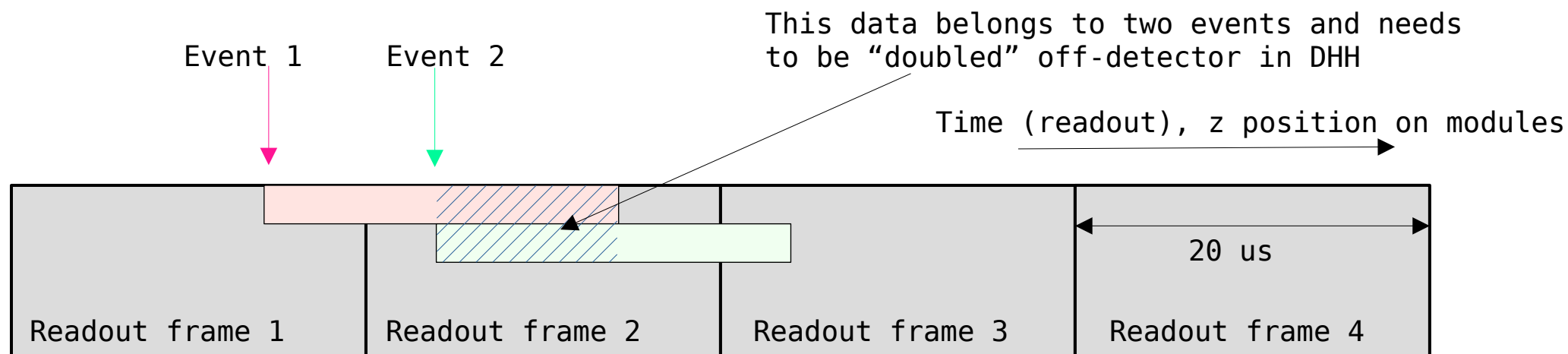
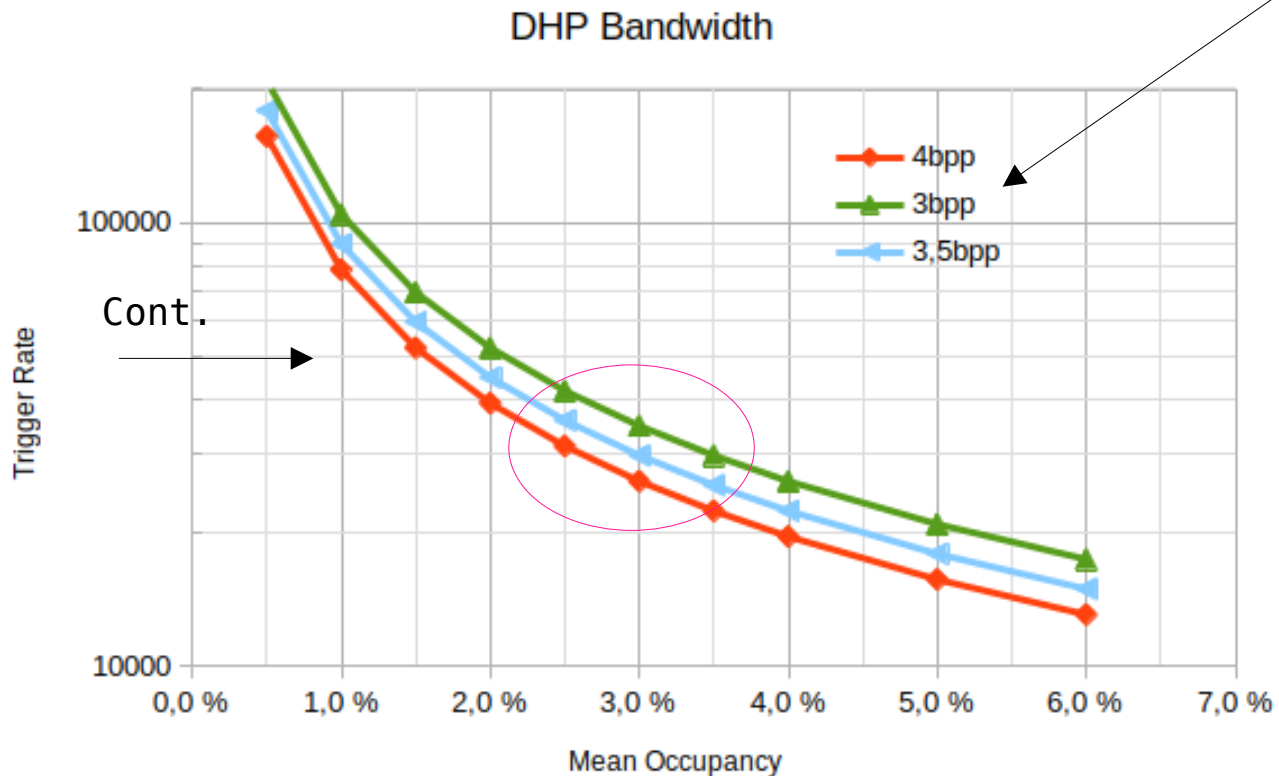


# Introduction: Detector and FEE Properties

- **Rolling shutter** readout: frame 20 us = 50 kHz (this is “trigger-less”)
  - Data is continuously sampled by DCD and written to DHP memory
  - **All data is always available from the DHP chip memory!**
- Classic “triggering”:
  - Tell the DHP which part of memory to send out → DHE takes care of formatting the data into “events”.
  - All data can (in principle) be read out, limited by DHP output FIFO and bandwidth between DHP and DHE
- **30 kHz trigger rate is “not far” from a continuous readout!**
  - (random trigger distribution: time wise overlap → 30 kHz is not 30/50 but more like 20/50 of overall data)





Depends on the distribution of hits on the sensor and cluster topology/size  
 4 - all unrelated  
 3 - realistic for large occupancy  
 $2 < x < 3$  - for injection noise

Overlapping trigger effects are not included, thus numbers  $> 20\text{kHz}$  are too pessimistic

We can never send out more data from the ASIC than in the continuous readout case, even if the trigger rate exceeds 30, 50, 100 kHz

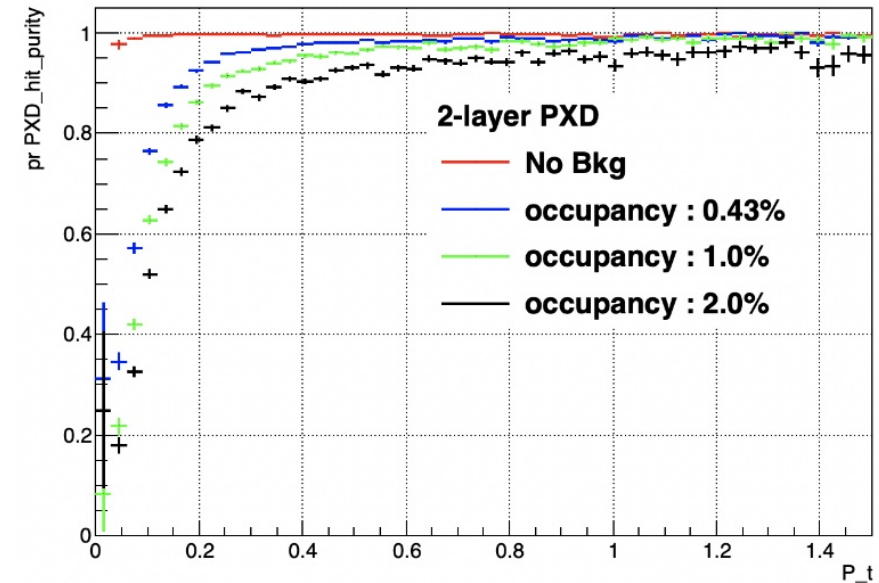
# (Short) Summary

- PXD readout on chip level is basically a free-running readout (trigger-less)
- PXD readout limited by ASIC (DHP) on modules and bandwidth to outside detector (DHH) above current design luminosity/background → this cannot be changed without building a new detector
- Within these limits, continuous readout (or trigger rates  $>50\text{kHz}$ ) would be in principle possible. But limitations on detector occupancy would apply (esp for inner layer) → we would lose our safety factor.
- Firmware would need to be rewritten (DHH). New concept for data reduction would be needed.
- Injection-trigger-veto currently saves us from the majority of high occupancy events. Some internal veto from DHE to DHP would be needed (similar to what is already in development).
- Remark 1: As the current limit is already on the ASIC soldered on the sensor, a new readout (new clustering hardware+direct input to EB1/HLT) will not change the picture.
- Remark 2: Any change in readout concept is unlikely to happen in view of a possible replacement of VXD with a different detector concept in the mid term future

- Some more details on where the limits arise ...

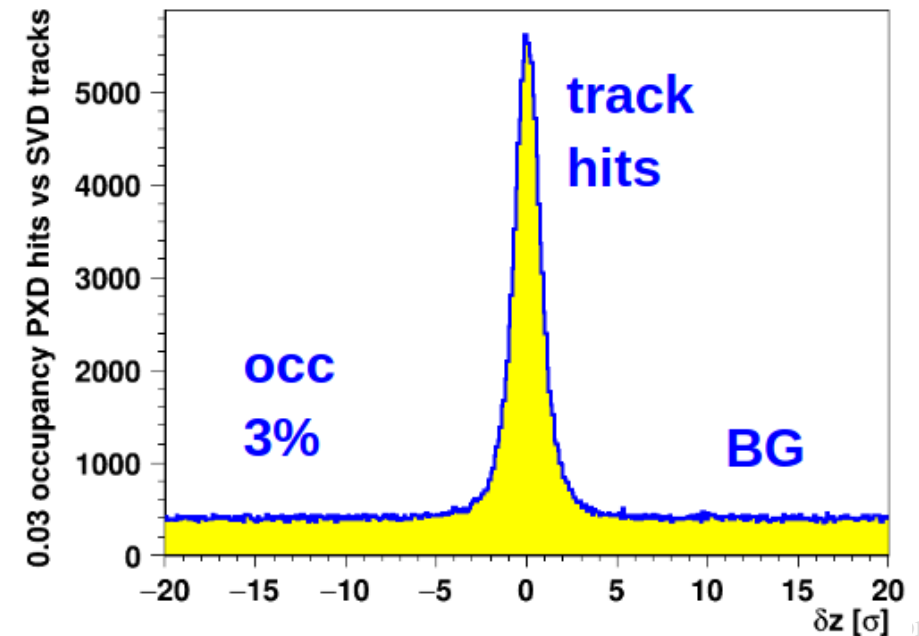
# The 3% Myth

- ~1% (in the inner layer!) expected from simulation, hardware design with safety factor at 3%.
- Same number applied for DHH/ONSEN etc
- Even below 3% tracking become worse (wrong hit assignment), lower purity
- PXD-DAQ can stand 3% @ 30kHz, but the resulting data would not be optimal.
- A 3% **mean** indicates that we have event with higher occupancy, injection noise with 30%(!) observed. Nowadays data is truncated at 4% +4%. Also within the detector the (local) occupancy varies.
- Several events triggered with >3% may clog FIFO due to bandwidth limit. → workaround: reset pipeline automatically after 2s of no-data



[https://indico.belle2.org/event/7891/contributions/47087/attachments/19199/28544/PXDANA\\_2-layerPXD\\_performance\\_20220117.pdf](https://indico.belle2.org/event/7891/contributions/47087/attachments/19199/28544/PXDANA_2-layerPXD_performance_20220117.pdf)

Residuals



- DHP → DHE
  - 1.5Gbit/DHP → 6.0Gbit per module (allows for >3% @ 30kHz)
  - Overlapping triggers; data belonging to two triggers is transmitted only once
- DHE → DHC
  - 40 x 2.5 Gbit (carrier design issue, hardware update in progress for 5 Gbit)
- DHC → ONSEN
  - 32 x 6.25 Gbit ; 620 MB/s/link ← works with load balancing
- ONSEN → EB2
  - 32 x 1 Gbit Ethernet. Expect only 30MB/s/link in worst case
  - 110MB/s tested with current system w/o any problems (back pressure to trigger)

System designed for 3%, 30 kHz @ full luminosity  
(3% includes safety margin from expected 1.5%)  
Occupancy L2 < L1, worst case scenario is inner layer  
L1/L2 allows for “load balancing” → downscale ONSEN 40→32 subunits

**No issue with projected occupancy/trigger rate**

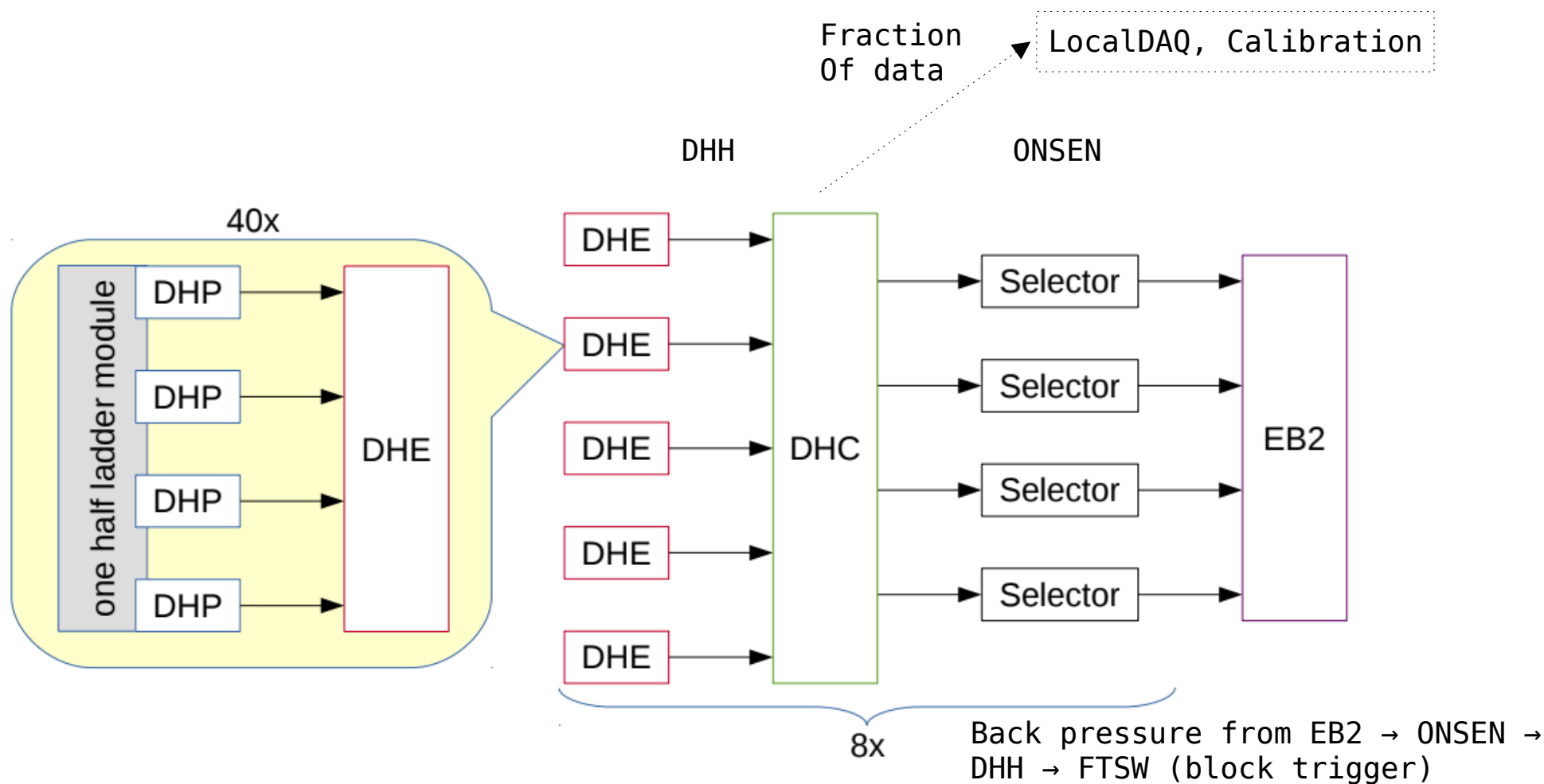
Todo: install DHH carrier fix and 2<sup>nd</sup> half of DHH

# Looking at Specific Bottlenecks

- DHP output:
  - Increasing trigger rate → saturates/approach maximum (=continuous readout)
  - Due to poisson-like trigger distribution (overlaps), even at 50 kHz (frame rate) not yet at maximum
  - Limit by data rate: exceeding 30kHz → 100 kHz (or continuous) would reduce the acceptable (mean) occupancy to  $\sim 1.5\%$  (depending on cluster topology)
- DHE/DHC
  - Design 3%@30kHz
  - Due to doubling of data of overlapping triggers, data rate scales linear with trigger rate
  - Continuous readout (need new firmware!) equivalent to 50kHz trigger rate
- ONSEN
  - Design 3%@30kHz with guaranteed HLT processing time
    - No direct limit on trigger rate if HLT decides fast enough
  - ROI filtering would not work for continuous readout, different concept needed

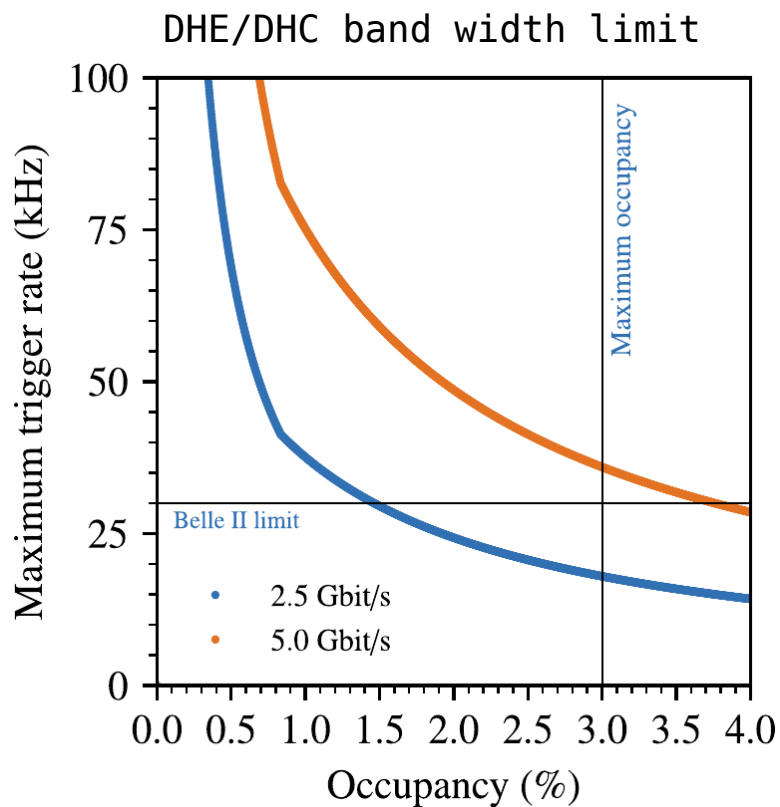
# PXD DAQ – Main Data Flow

- Module (DHP ASIC)
- DHH
- ONSEN
- (HLT/DATCON → ONSEN not shown)

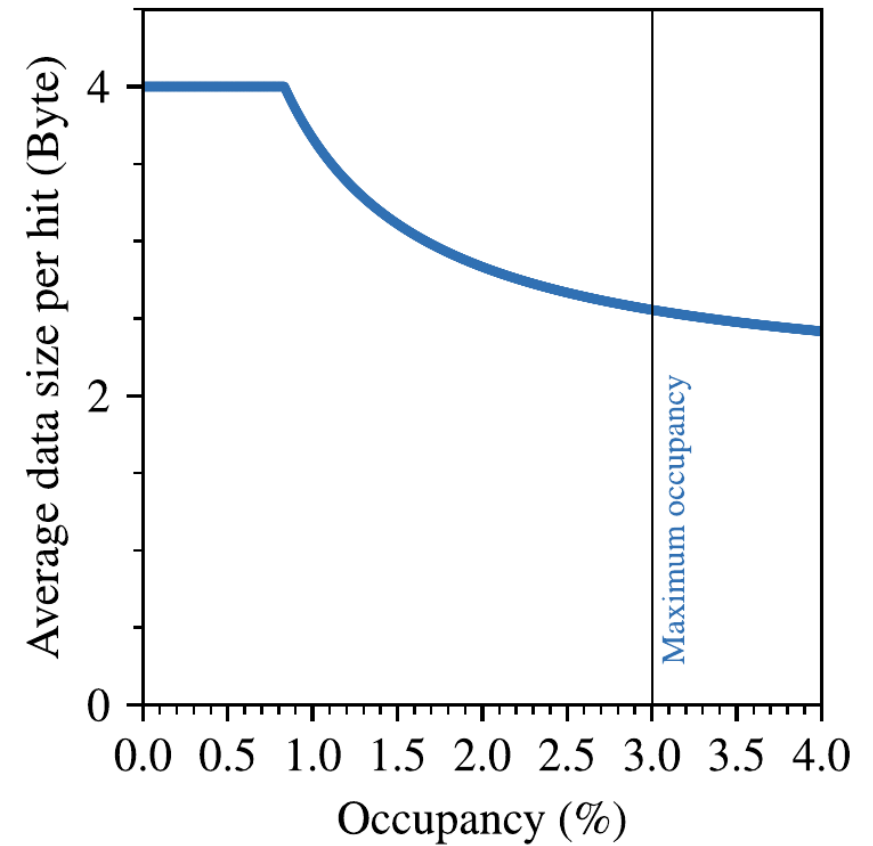




- Worst case size per hit vs occupancy
- DHE/DHC band width limit



Worst case size per hit vs occupancy



- Remaining slides need to be updated and re-checked or removed

- Data Rates  $\leftrightarrow$  Occupancy
  - Defined by data format
- Mean data rates  $\neq$  Maximum data rates
  - Instant peak values (f.e. injection spikes)
  - “Bursts” of large events
- Distribution of Occupancy not flat
  - Inner layer  $>$  outer layer
  - Z and Phi dependence
  - Spikes, rolling shutter looks 20us into past/future
- Tracking:
  - Local occupancy is important for track matching, cluster overlapping
  - Random distribution of pixel vs clusters (cluster size)

# Example

- Assume 1% Occupancy uniform in all layers,  $\sim 1$  hit per DHP double row  $\rightarrow \sim 4$  bytes/pixel
- $N_{\text{pixel}} = 768 * 250 * 1\% / 4 = 480$  pixel per DHP
- $20 * 4 * 480 * 4 \text{ bytes} = 153600$  bytes (20 modules, 4 DHP)
- Sum: 156224 bytes /event
- $\rightarrow 1.7\%$  is overhead
  
- Data rate depends on trigger rate:
- Assume 30 kHz and no ROI selection, HLT filtering 1/3:  
 $\rightarrow 4686 * 10^6$  bytes/s,  $1562 * 10^6$  bytes/s (filtered)
- 16 links  $\rightarrow$  EB2:  $98 * 10^6$  bytes/s/link
- DHC  $\rightarrow$  ONSSEN (16 links):  $293 * 10^6$  bytes/s/link
- DHE  $\rightarrow$  DHC (20 links):  $234 * 10^6$  bytes/s/link

1/3 is very conservative  
Ongoing run is 1/11  
( $\sim 1/8$  in size)

# Example PXD2

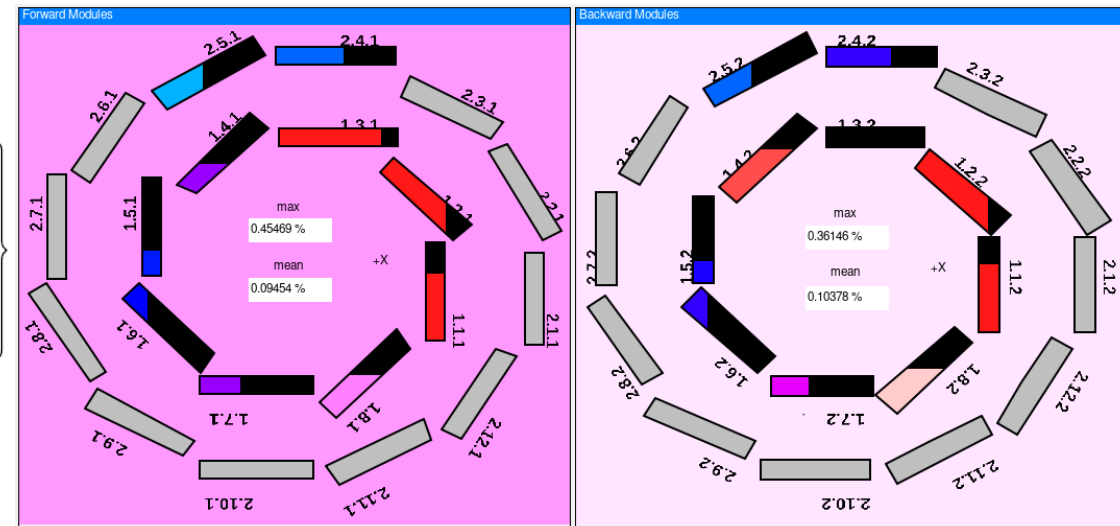
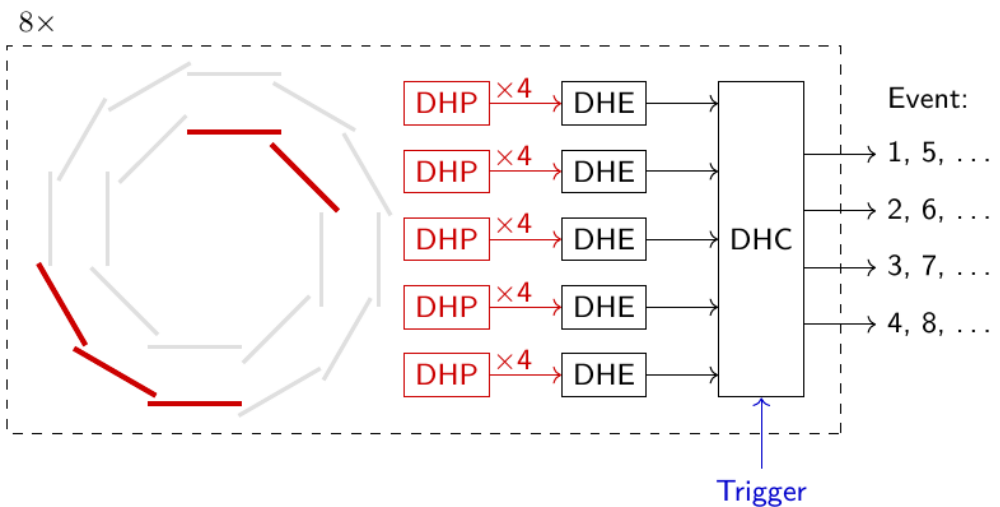
- Assume 3% Occupancy uniform in all layers, ~1 hit per DHP double row → ~4 bytes/pixel
- $N_{\text{pixel}} = 768 * 250 * 3\% / 4 = 1440$  pixel per DHP
- $40 * 4 * 1440 * 4 \text{ bytes} = 921600$  bytes (20 modules, 4 DHP)
- → 0.6% is overhead (ignored)
  
- Data rate depends on trigger rate:
- Assume 30 kHz and with ROI selection, HLT filter
- →  $27.6 * 10^9$  bytes/s
- 32 links → EB2, ROI red to 10%, HLT filter 1/3:
  - $29 * 10^6$  bytes/s/link
  - DHC → ONSSEN (32 links):  $866 * 10^6$  bytes/s/link
  - DHE → DHC (40 links):  $693 * 10^6$  bytes/s/link

1/3 is very conservative  
Ongoing run is 1/11  
(~1/8 in size)

DAQ group requested header  
data for rejected events  
→ some additional overhead is  
missing here

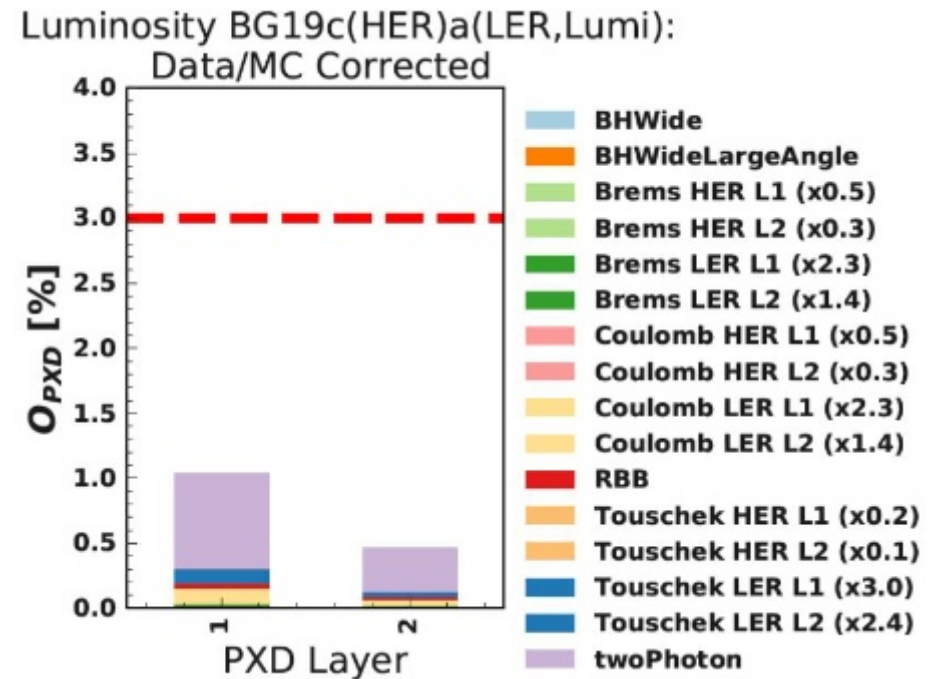
# Remarks

- Worst case assumptions for design consideration!
- **Mean** rate of the most busy module should not exceed 3%
- 3% was already including a safety margin
- Optimization
  - Outer layer < inner layer ; phi dependence:
    - → Load balancing (2 inner + 3 outer modules in one DHC), reduces mean rate on DHC output



# Occupancy / Background Projection

- We will not reach 3% at design luminosity (Analysis by Sally → Talk by Lu Cao)
- (and our final luminosity may be lower)

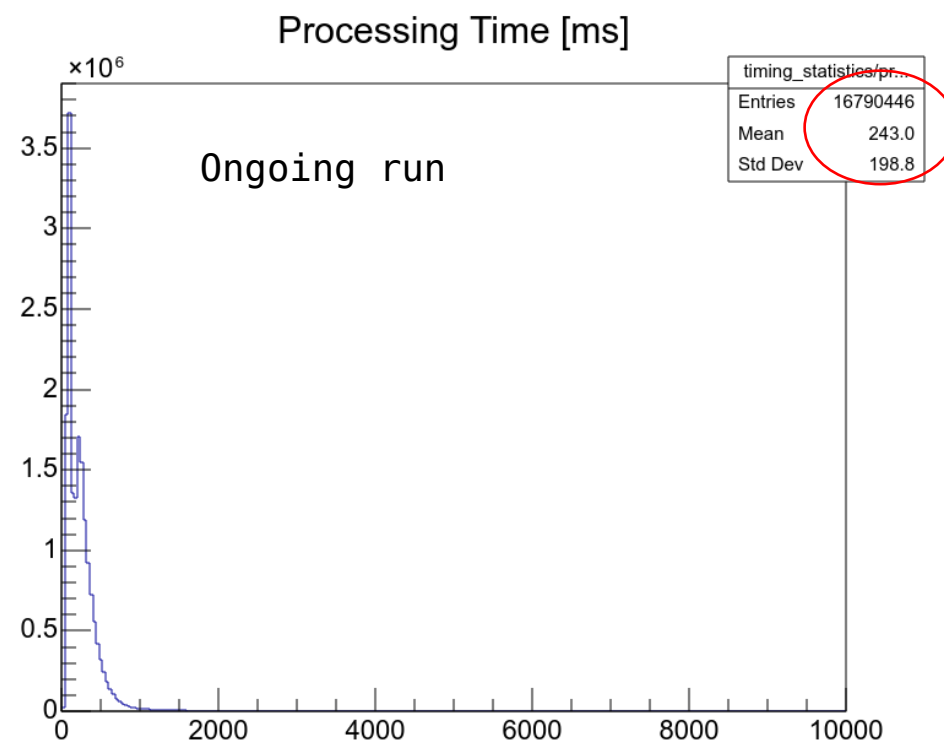


# Buffering for HLT Decision/ROI Filtering

- PXD data is buffered in ONSSEN until HLT decision (ROIs)
  - $1.5\text{GB} * 16 (32) = 24 (48)\text{GB}$
  - LUT for 30s @ 30kHz
- Memory occupancy depends on event size (occupancy), trigger rate and HLT (mean) processing time
  - Assume 1MB size (3% for 20 mod)
    - → 24000 events can be stored at a given time
  - Assume 30kHz trigger rate
    - → accept 800ms mean delay for HLT decision
- Hard to predict the future HLT processing time
  - Newer hardware, change in software etc
  - Tracking complexity for busy events

Combination of mean event size,  
mean processing time and trigger rate  
determines buffer occupancy.

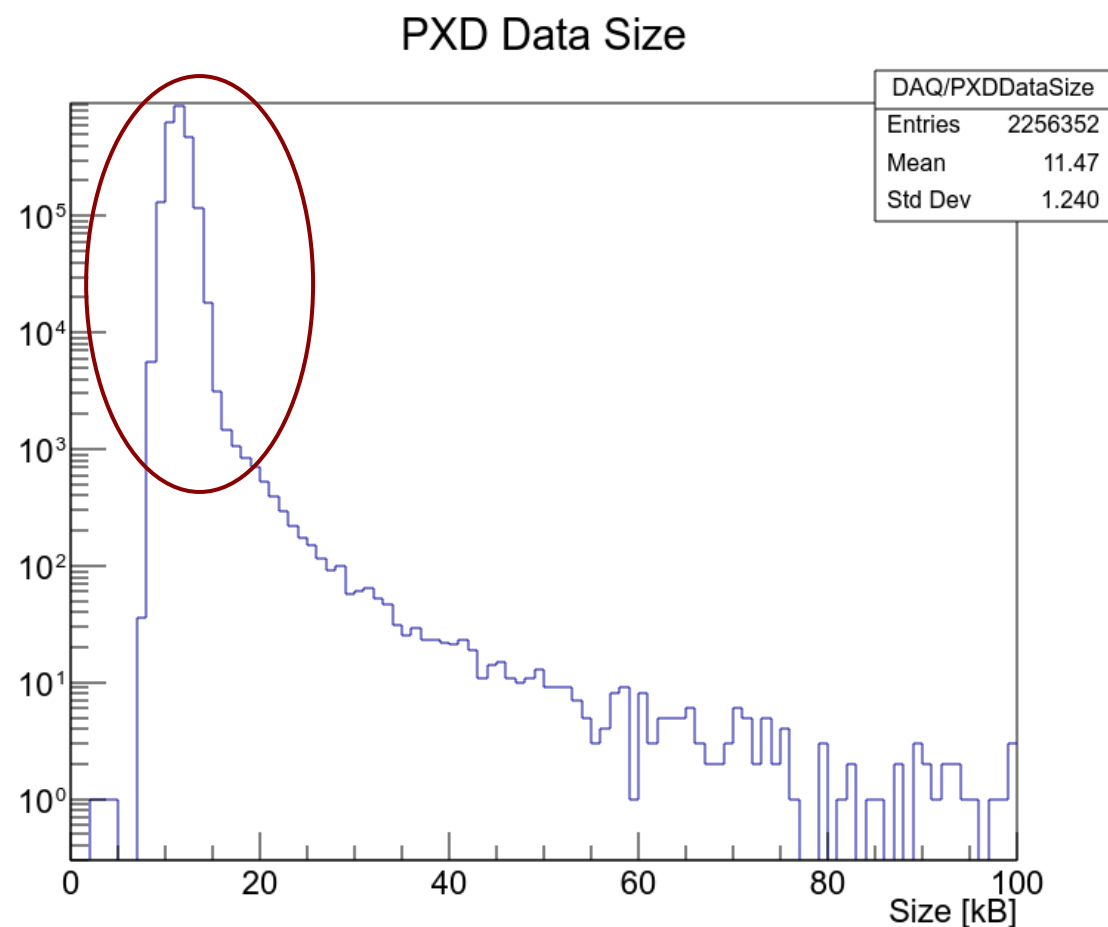
No issue as long as HLT is fast enough.



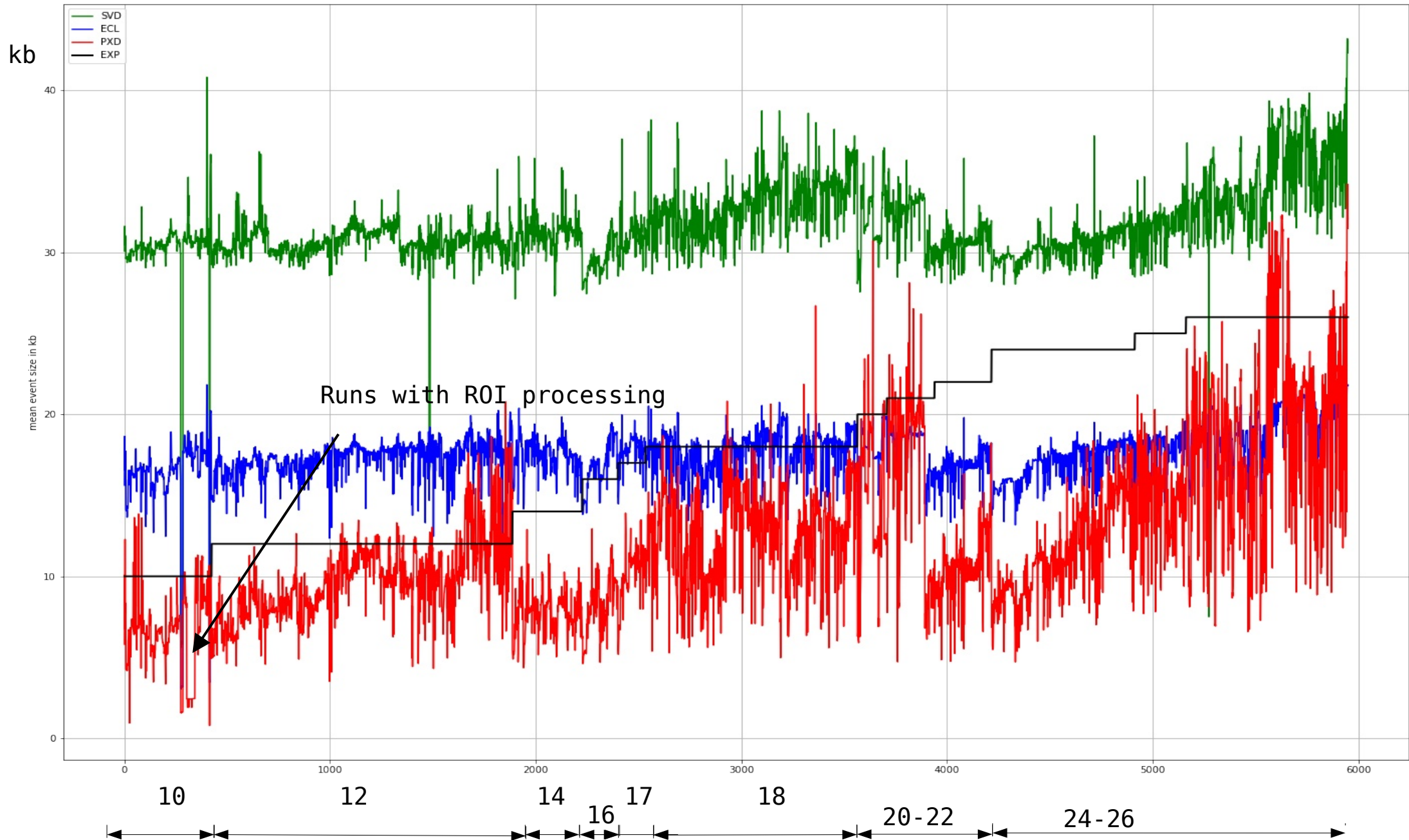


# Other Limits

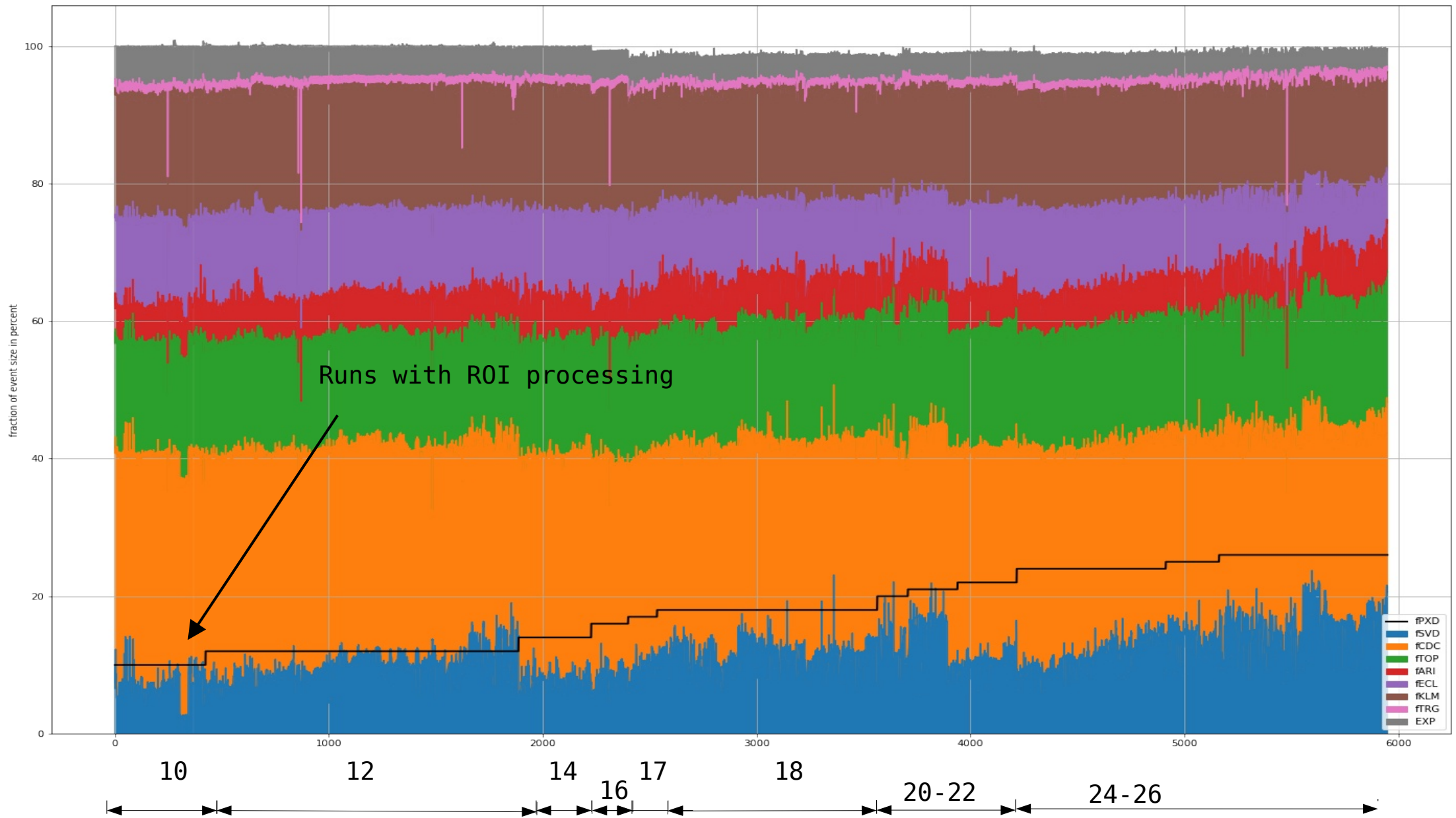
- Event (storage) size, fraction of PXD in raw data
- Tapes = Money, thus no principle design problem



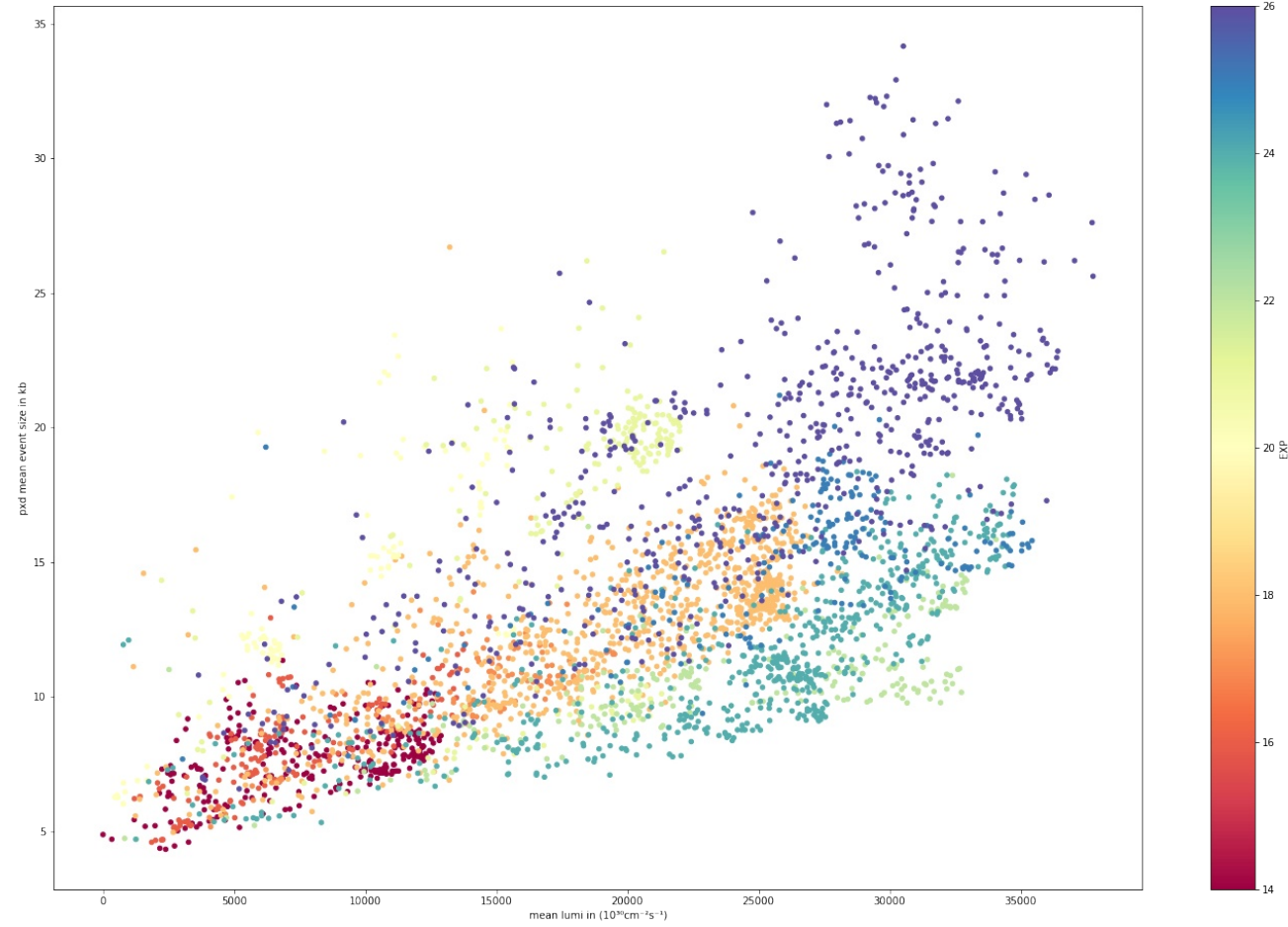
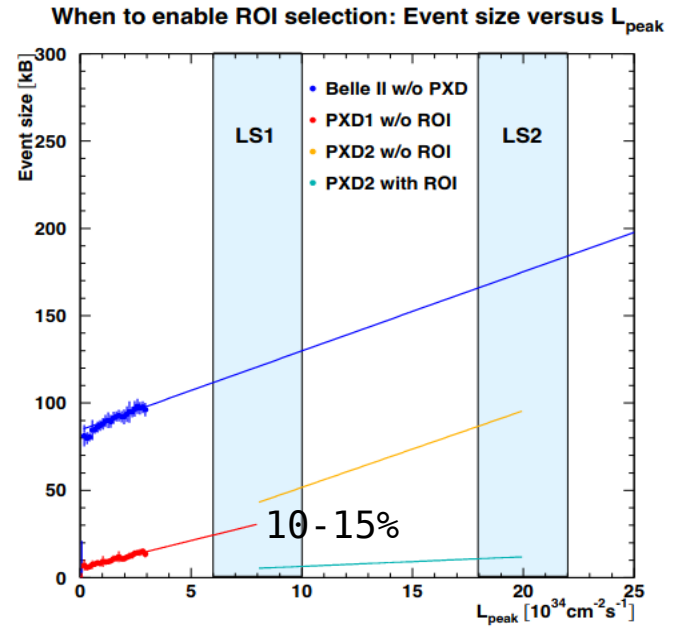
# Exp 10 – 18, Raw Size (in kb)



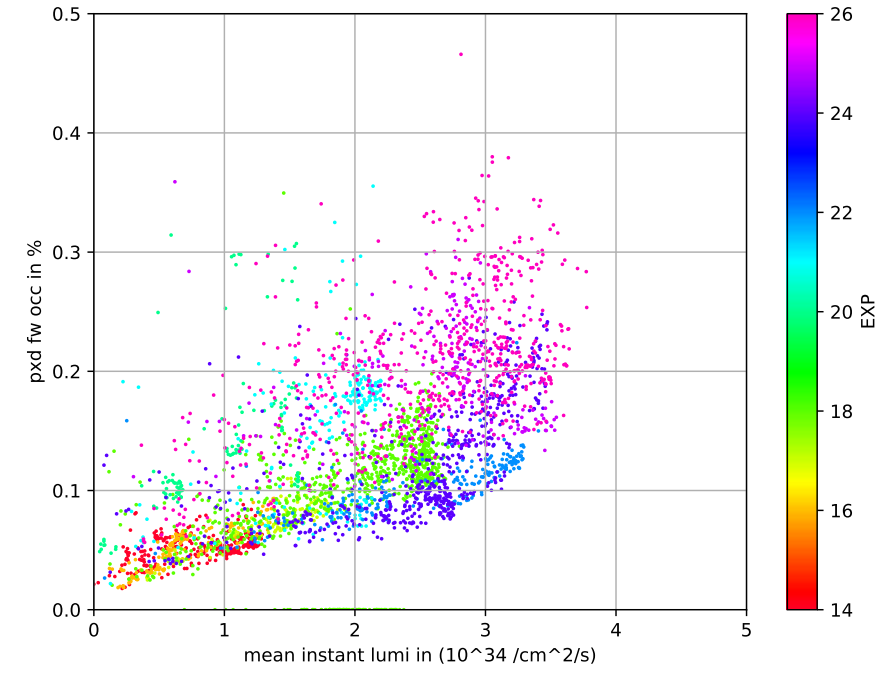
# Exp 10 – 16, Fraction of Raw Size



- Plotting against Lumiosity
- Seems PXD data is not the major contributor to overall event size
- No need to turn on ROI filtering in the near future

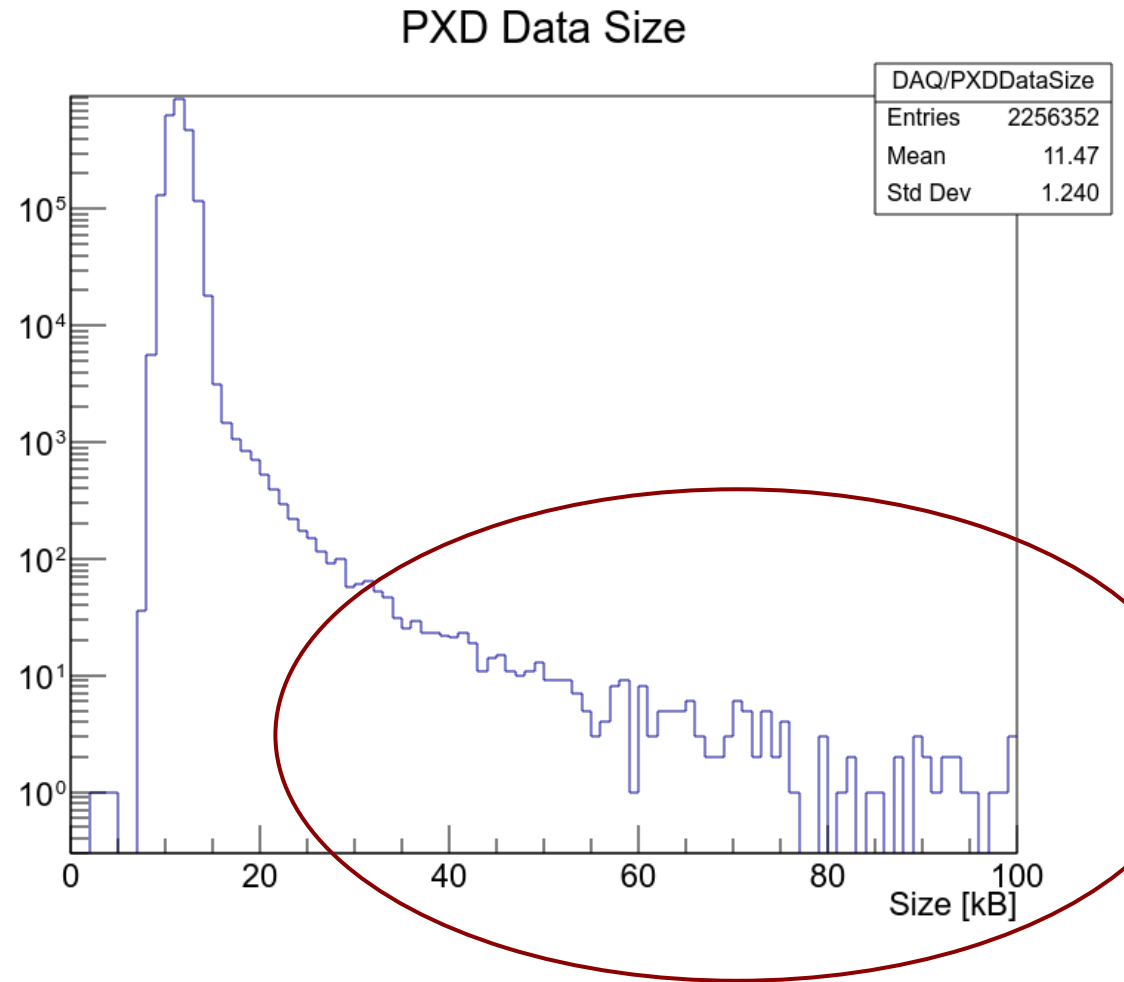


Be aware that this maybe an

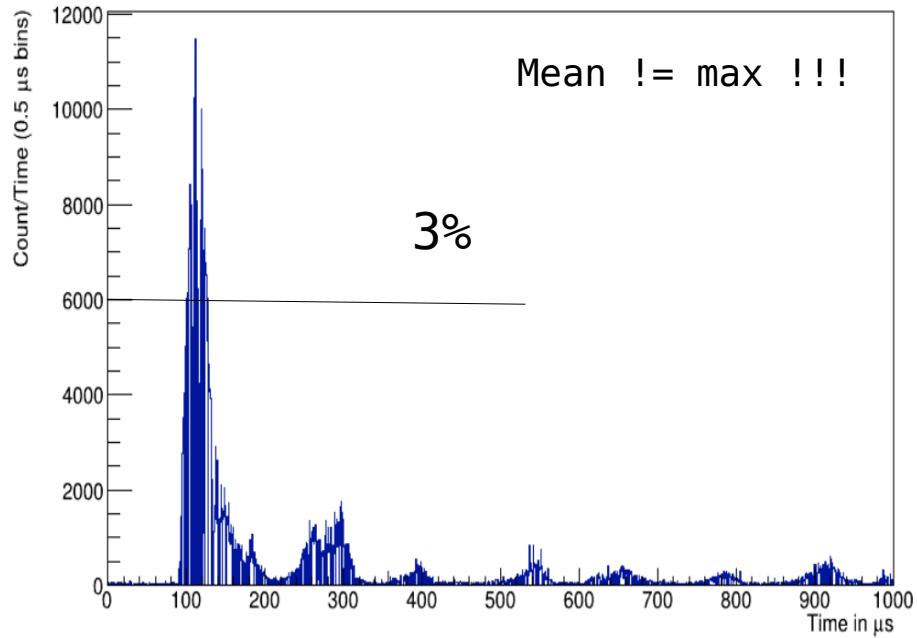


# Other Limits

- Injection spikes
- Few but large events
- (has nothing do to with slow pion reconstruction)

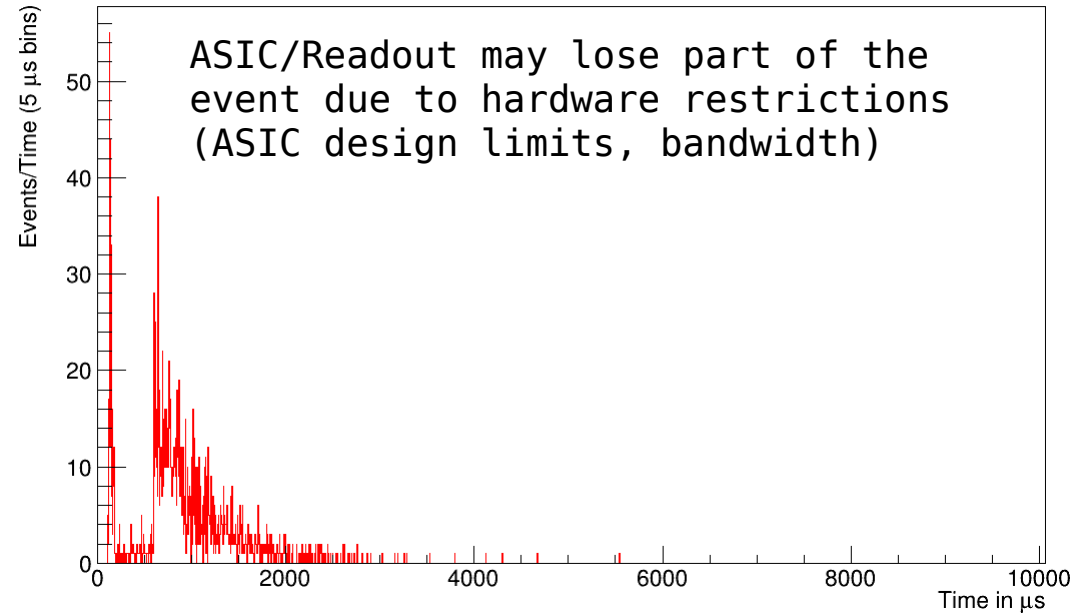


MeanOccLER 1\_1\_1 Setting0\_4172\_noGM\_Th20\_Offset25\_NTO67\_NTL35\_GML16

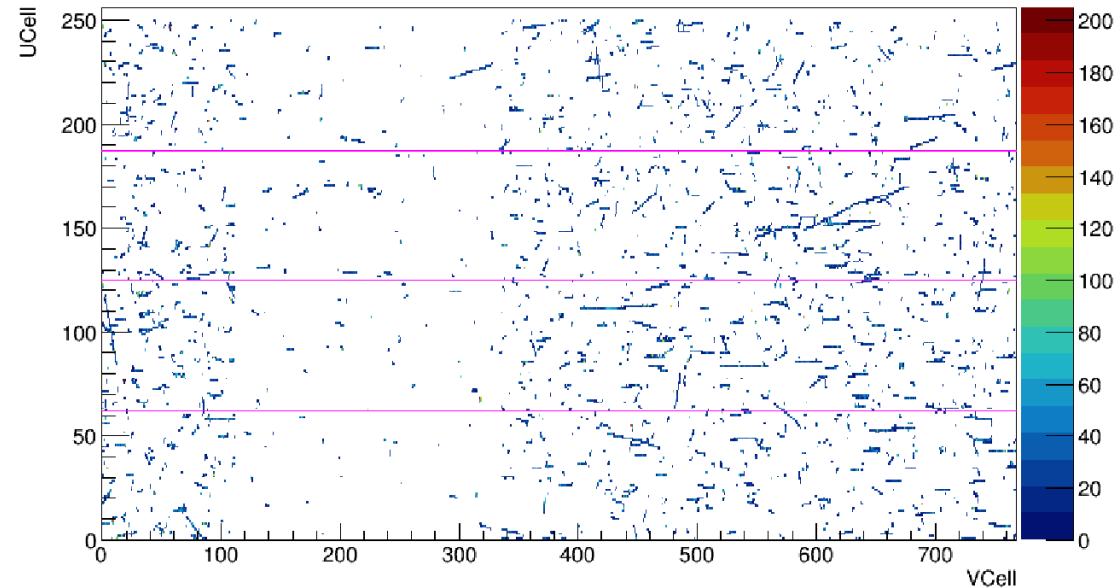


Events close to injection may exceed 3% by far (30% and more observed)

PXDMissInjHER/Time



Non uniform occ by rolling shutter

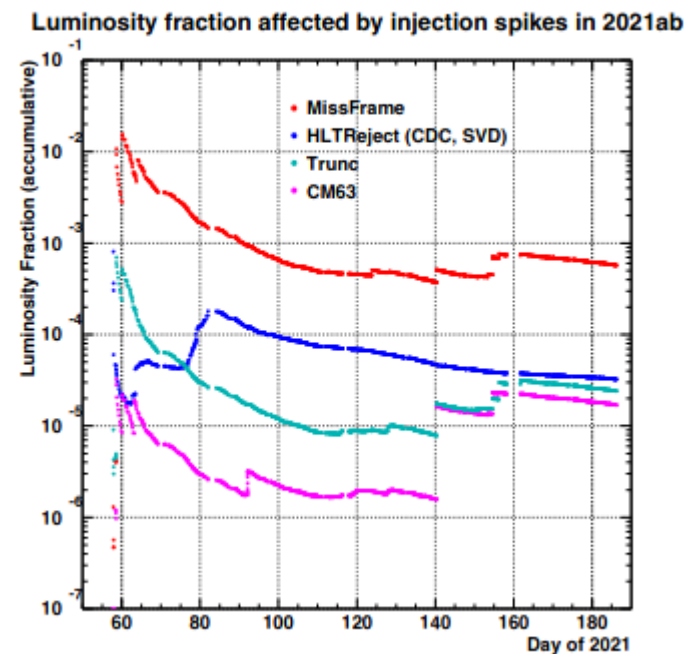
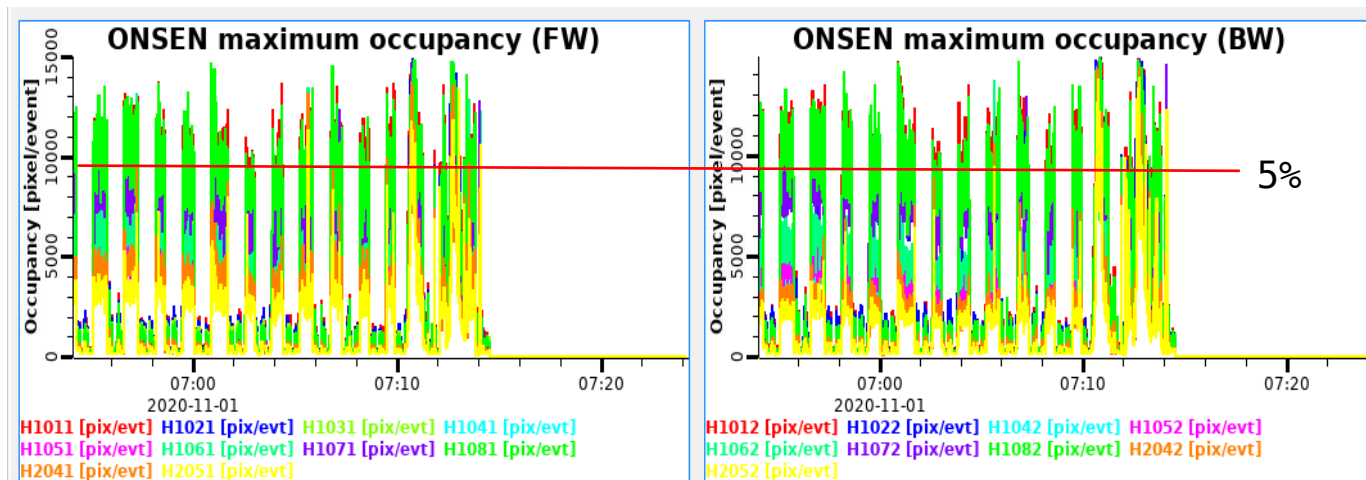




# Injection Backgrounds

- Overall background not an issue to PXD in the foreseeable future
  - Data rate acceptable even w/o ROI selection for the moment
  - Injection (spikes) background poses other problems, e.g. events  $\gg 3\%$
- Limits:
  - DHP Fifo; DHP  $\rightarrow$  DHE, frame nr slip
  - DHP Fifo  $\rightarrow$  CM63 error (we need much more than 3% to trigger this)
  - Frame Nr slip happens if we have overlapping triggers with huge occupancy  $\rightarrow$  readout one frame takes so long that frame counter increased twice  $\rightarrow$  cannot match frame to trigger
- Unphysical events can be truncated only on DHE input (currently:  $2 \cdot 5\%$ )
  - Losses typically dominated by handful of incidents
  - No issue for PXD DAQ stability!

**This will not change with clustering/PCle readout**



# Truncated Event

- Events exceeding a defined occupancy (here 3% per DHP frame) are truncated to prevent congestion in DHE

